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On affine translation hypersurfaces of constant mean curvature

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Abstract. The purpose of this paper is to classify the affine translation hypersurfaces with nonzero constant mean curvature.

1. Introduction

An *n*-dimensional hypersurface in E^{n+1} is called a translation hypersurface if it is obtained as the graph of the function $F(x_1, \ldots, x_n) = f_1(x_1) + \cdots + f_n(x_n)$, where $f_1(x_1), \ldots, f_n(x_n)$ are differentiable functions. A hypersurface is said to be minimal if its mean curvature is zero identically. As well known, a minimal translation surface in the 3-dimensional Euclidean space E^3 must be a plane or a surface which is the graph of the function $F(x_1, x_2) = \frac{1}{a}(\ln \cos(ax_1) - \ln \cos(ax_2))$, where *a* is a nonzero constant. For a translation hypersurface *M* with constant mean curvature in E^{n+1} , we have obtained [2]

(1) when M is minimal, then $F(x_1, \ldots, x_n)$ is a linear function or

$$F(x_1, \dots, x_n) = \frac{1}{a} \ln \frac{\cos(ax_1)}{\cos(ax_2) \dots \cos(ax_k)} + c_{k+1}x_{k+1} + \dots + c_nx_n,$$

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(2) when M is not minimal, then

$$F(x_1, \dots, x_n) = -\frac{\sqrt{1+a^2}}{2H}\sqrt{1-4H^2x_1^2} + ax_2 + a_3x_3 + \dots + a_nx_n,$$

where $a, c_{k+1}, \ldots, c_n, a_3, \ldots, a_n$ are constant. Naturally, one can consider the similar problem: to classify affine translation hypersurfaces in the affine space R^{n+1} . Of course, the case of affine hypersurfaces in R^{n+1} is more complicated than that of hypersurfaces in E^{n+1} . In [7], F. MANHART studied nondegenerate affine minimal translation surfaces in an affine space R^3 and gave a complete classification.

As a generalization, W. YANG and D. QIU [11] classified affine minimal translation hypersurfaces in \mathbb{R}^{n+1} .

In [10] and [9], the first author of this paper and H. PABEL classified the affine translation surfaces with nonzero constant mean curvature in \mathbb{R}^3 , respectively.

The purpose of the present paper is to classify affine translation hypersurfaces in \mathbb{R}^{n+1} with nonzero constant mean curvature. Our main result is:

Theorem. Let M be an n-dimensional nondegenerate affine translation hypersurface with nonzero constant mean curvature in \mathbb{R}^{n+1} . Then up to affine transformations, M is the graph of the following function:

$$x_{n+1} = \alpha \int_{x_0}^{x_1} \left\{ \int_{t_0}^t \left(Hs^2 + a_1 \right)^{-\frac{n+2}{n+1}} ds \right\} dt + a_2 x_2^2 + \dots + a_n x_n^2,$$

where α, a_1, \ldots, a_n are constant and $H(\neq 0)$ is the affine mean curvature of M in \mathbb{R}^{n+1} .

2. Preliminaries

Let $f: M \to \mathbb{R}^{n+1}$ be an immersion of a connected differentiable *n*manifold M into the affine space \mathbb{R}^{n+1} equipped with usual flat connection D and a parallel volume element ω , and let ξ be an arbitrary local field of transversal vector to f(M). For any vector fields X, Y on M, we write

$$D_X f_*(Y) = f_*(\nabla_X Y) + h(X, Y)\xi, \qquad (2.1)$$

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$$D_X \xi = -f_*(SX) + \tau(X)\xi, \qquad (2.2)$$

Thus we have an affine connection ∇ , a symmetric tensor h of type (0, 2), a tensor S of type (1.1) and 1-form τ on M. We call h, S and τ the affine fundamental form, the affine shape operator and the transversal connection form, respectively. We define by $H = \frac{1}{n}$ trace S the affine mean curvature of M. We call M affine minimal if H is zero identically. We define a volume element θ on M by

$$\theta(X_1, \dots, X_n) = \omega(f_*(X_1), \dots, f_*(X_n), \xi)$$

= det(f_*(X_1), \dots, f_*(X_n), \xi), (2.3)

for any tangent vectors X_1, \ldots, X_n to M.

We say that f is nondegenerate if h is nondegenerate. This nondegeneracy does not depend on the choice of ξ . If f is nondegenerate, it is known that there is a unique ξ up to sign such that the corresponding induced connection ∇ , the affine fundamental form h, and the induced volume element θ satisfy

- (i) $\nabla \theta = 0$, thus (∇, θ) is an equiaffine structure on M.
- (ii) $\theta = \omega_h, \ \omega_h(X_1, \dots, X_n) = |\det(h(X_i, X_j))|^{\frac{1}{2}}$ (volume element given by h).

We call such ξ the affine normal of f. Condition (i) implies that $\tau = 0$ so that $D_X \xi = -f_*(SX)$.

Let $x_{n+1} = F(x_1, \ldots, x_n)$ be a differentiable function on a domain $D \subset \mathbb{R}^n$. We shall determine the affine normal of an immersion

$$f: D \ni (x_1, \dots, x_n) \mapsto (x_1, \dots, x_n, F(x_1, \dots, x_n)) \in \mathbb{R}^{n+1}$$

We start with a tentative choice of transversal field $\xi = (0, ..., 0, 1)$. Since $D_{\partial_i}\xi = 0$, we have $\tau = 0$. Denote by ∂_j the coordinate vector field $\partial/\partial x_j$. Then we have

$$f_*(\partial_1) = (1, 0, \dots, 0, F_1), \dots, f_*(\partial_n) = (0, \dots, 0, 1, F_n),$$

where $F_j = \partial F / \partial x_j$. Thus we get

$$D_{\partial_i}f_*(\partial_j) = (0, \dots, 0, F_{ij}) = F_{ij}\xi, \quad F_{ij} = \frac{\partial^2 F}{\partial x_i \partial x_j},$$

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and

$$\nabla_{\partial_i}(\partial_j) = 0, \quad h(\partial_i, \partial_j) = F_{ij}.$$

Thus the immersion is nondegenerate if and only if $\det(F_{ij}) \neq 0$. We find that

$$\theta(\partial_1,\ldots,\partial_n) = \det(f_*(\partial_1),\ldots,f_*(\partial_n),\xi) = 1.$$

Hence taking $\phi = |\det(F_{ij})|^{\frac{1}{n+2}}$, we can find Z such that $\phi\xi + Z = \overline{\xi}$ is the affine normal field and $\overline{\xi}$ is given by

$$\bar{\xi} = -\sum_{j,k} \left(F^{kj} \phi_j \right) f_*(\partial_k) + \phi \xi,$$

where $\phi_j = \partial \phi / \partial x_j$, (F^{ij}) is the inverse of the matrix (F^{ij}) . From which we have

$$D_{\partial_i}\bar{\xi} = -\sum_{j,k} \partial_i \left(F^{kj}\phi_j\right) f_*(\partial_k)$$

and

$$S(\partial_i) = \sum_{j,k} \partial_i \left(F^{kj} \phi_j \right) \partial_k$$

Hence we see that the affine mean curvature of M satisfies

$$H = \frac{1}{n} \sum_{i,j} \partial_i \left(F^{ij} \phi_j \right).$$
(2.4)

3. Proof of the main theorem

Throughout this section, we assume that M is a translation hypersurface, i.e., it is obtained as the graph of function $F(x_1, \ldots, x_n) = f_1(x_1) + \cdots + f_n(x_n)$, where f_1, \ldots, f_n are differentiable functions. Thus we have

$$(F_{ij}) = \begin{pmatrix} f_1''(x_1) & 0 \\ & \ddots & \\ 0 & f_n''(x_n) \end{pmatrix},$$
$$(F^{ij}) = (F_{ij})^{-1} = \begin{pmatrix} (f_1''(x_1))^{-1} & 0 \\ & \ddots & \\ 0 & (f_n''(x_n))^{-1} \end{pmatrix},$$

and from the nondegeneracy assumption, we have

$$\phi = |\det(F_{ij})|^{\frac{1}{n+2}} = \left| f_1''(x_1) \dots f_n''(x_n) \right|^{\frac{1}{n+2}}$$

never vanishes, so the f''_i 's never vanish either. Let $G_i = \varepsilon_i f_i$ satisfy $G''_i = \varepsilon_i f''_i = |f''_i|$, where $\varepsilon_i = 1$ when $f''_i > 0$ and $\varepsilon_i = -1$ when $f''_i < 0$. Thus we get

$$\phi_i = \frac{1}{n+2} G_i''^{-1} G_i''' (G_1'' \dots G_n'')^{\frac{1}{n+2}}$$

and

$$\phi_{ii} = \frac{1}{n+2} (G_1'' \dots G_n'')^{\frac{1}{n+2}} \left(-\frac{n+1}{n+2} G_i''^{-2} G_i'''^2 + G_i''^{-1} G_i^{(4)} \right).$$

Therefore, by a direct calculation we have

$$\begin{split} nH &= \sum_{i} \partial_{i} \left(F^{ii} \phi_{i} \right) = \sum_{i} \left((\partial_{i} F^{ii}) \phi_{i} + F^{ii} \phi_{ii} \right) \\ &= \frac{1}{n+2} (G_{1}^{\prime \prime} \dots G_{n}^{\prime \prime})^{\frac{1}{n+2}} \\ &\cdot \sum_{i} \left(-\frac{f_{i}^{\prime \prime \prime \prime}}{f_{i}^{\prime \prime \prime 2}} G_{i}^{\prime \prime \prime \prime} G_{i}^{\prime \prime -1} - \frac{n+1}{n+2} f_{i}^{\prime \prime -1} G_{i}^{\prime \prime -2} G_{i}^{\prime \prime \prime 2} + f_{i}^{\prime \prime -1} G_{i}^{\prime \prime -1} G_{i}^{(4)} \right) \\ &= \frac{1}{n+2} \left(G_{1}^{\prime \prime \prime} \dots G_{n}^{\prime \prime} \right)^{\frac{1}{n+2}} \sum_{i} \left(-\frac{\varepsilon_{i} G_{i}^{\prime \prime \prime 2}}{G_{i}^{\prime \prime 3}} - \frac{n+1}{n+2} \frac{\varepsilon_{i} G_{i}^{\prime \prime \prime 2}}{G_{i}^{\prime \prime 3}} + \frac{\varepsilon_{i} G_{i}^{(4)}}{G_{i}^{\prime \prime 2}} \right) \\ &= \frac{1}{n+2} \left(G_{1}^{\prime \prime} \dots G_{n}^{\prime \prime} \right)^{\frac{1}{n+2}} \sum_{i} \left(-\frac{2n+3}{n+2} \frac{\varepsilon_{i} G_{i}^{\prime \prime \prime 2}}{G_{i}^{\prime \prime 3}} + \frac{\varepsilon_{i} G_{i}^{\prime \prime 4}}{G_{i}^{\prime \prime 2}} \right) \\ &= \left(G_{2}^{\prime \prime} \dots G_{n}^{\prime \prime} \right)^{\frac{1}{n+2}} \varepsilon_{1} G_{1}^{\prime \prime -\frac{3n+5}{n+2}} \left(-\frac{2n+3}{n+2} G_{i}^{\prime \prime \prime 2} + G_{i}^{\prime \prime} G_{i}^{\prime \prime 4} \right) \\ &+ \left(G_{1}^{\prime \prime} G_{3}^{\prime \prime} \dots G_{n}^{\prime \prime} \right)^{\frac{1}{n+2}} \varepsilon_{2} G_{2}^{\prime \prime -\frac{3n+5}{n+2}} \left(-\frac{2n+3}{(n+2)^{2}} G_{2}^{\prime \prime \prime 2} + \frac{1}{n+2} G_{1}^{\prime \prime} G_{1}^{\prime \prime 4} \right) \\ &+ \dots \\ &+ \left(G_{1}^{\prime \prime} \dots G_{n-1}^{\prime \prime} \right)^{\frac{1}{n+2}} \varepsilon_{n} G_{n}^{\prime \prime -\frac{3n+5}{n+2}} \left(-\frac{2n+3}{(n+2)^{2}} G_{n}^{\prime \prime \prime 2} + \frac{1}{n+2} G_{n}^{\prime \prime} G_{n}^{\prime \prime 4} \right) \end{split}$$

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so we have

$$nH = (G_2'' \dots G_n'')^{\frac{1}{n+2}} Q_1(x_1) + \dots + (G_1'' \dots G_{n-1}'')^{\frac{1}{n+2}} Q_n(x_n), \quad (3.1)$$

where

$$Q_i(x_i) = \varepsilon_i G_i^{'' - \frac{3n+5}{n+2}} \left(-\frac{2n+3}{(n+2)^2} G_i^{'''2} + \frac{1}{n+2} G_i^{''} G_i^{(4)} \right).$$
(3.2)

In order to prove our Theorem, we need the following Lemma.

Lemma. If H is a non-zero constant, then there exists $i \ (i = 1, ..., n)$ such that $G_i'' \neq 0$ and $G_j'' = 0$ for $j \neq i$.

PROOF. We first prove that if all $G_i'' \neq 0$, then H = 0. In fact, differentiating (3.1) with respect to x_i we get

$$0 = (G_1'' \dots G_{i-1}'' G_{i+1}'' \dots G_n'')^{\frac{1}{n+2}} Q_i'(x_i) + \frac{1}{n+2} G_i''^{\frac{1}{n+2}-1} G_i''' \Big[(G_2'' \dots G_{i-1}'' G_{i+1}'' \dots G_n'')^{\frac{1}{n+2}} Q_1(x_1) + \dots + (G_1'' \dots G_{i-1}'' G_{i+1}'' \dots G_{n-1}'')^{\frac{1}{n+2}} Q_n(x_n) \Big]$$

from which we get

$$-\frac{(n+2)Q'_{i}(x_{i})}{G_{i}^{''-\frac{n+1}{n+2}}G_{i}^{'''}} = \frac{Q_{1}(x_{1})}{G_{1}^{''\frac{1}{n+2}}} + \dots + \frac{Q_{i-1}(x_{i-1})}{G_{i-1}^{''\frac{1}{n+2}}} + \frac{Q_{i+1}(x_{i+1})}{G_{i+1}^{''\frac{1}{n+2}}} + \dots + \frac{Q_{n}(x_{n})}{G_{n}^{''\frac{1}{n+2}}}.$$
(3.3)

Differentiating (3.3) with respect to x_j , we can get easily that

$$\left(\frac{Q_j(x_j)}{G_j^{\prime\prime}\frac{1}{n+2}}\right)'_{x_j} = 0, \qquad j \neq i.$$

In the other hand, changing i to $k \ (k \neq i)$ in (3.3) and differentiating with respect to x_j , we get

$$\left(\frac{Q_j(x_j)}{G_j^{''\frac{1}{n+2}}}\right)'_{x_j} = 0, \qquad j \neq k.$$

From the above two formulas, we can get

$$\left(\frac{Q_j(x_j)}{G_j'^{\frac{1}{n+2}}}\right)' = 0 \qquad j = 1, \dots, n.$$
(3.4)

And so

$$Q_j(x_j) = c_j G_j^{''\frac{1}{n+2}}, \qquad (j = 1, \dots, n),$$
 (3.5)

where c_j 's are constant. From (3.5) we get

$$Q'_{j}(x_{j}) = \frac{1}{n+2} c_{j} G_{j}^{'' - \frac{n+1}{n+2}} G_{j}^{'''}.$$
(3.6)

Therefore, combining (3.3), (3.5) with (3.6) we can get

$$c_1 + \dots + c_n = 0. \tag{3.7}$$

Combining (3.1), (3.5) with (3.7) we get

$$nH = (G_1'' \dots G_n'')^{\frac{1}{n+2}} (c_1 + \dots + c_n) = 0,$$

and so H = 0.

Then we assume that $G_n'''(x_n) = 0$. In this case, $G_n'' = d_n = \text{constant}$ and $Q_n(x_n) = 0$. From (3.1) we get

$$nHd_n^{-\frac{1}{n+2}} = (G_2'' \dots G_{n-1}'')^{\frac{1}{n+2}} Q_1(x_1) + \dots + (G_1'' \dots G_{n-2}'')^{\frac{1}{n+2}} Q_{n-1}(x_{n-1}).$$
(3.8)

If $G_i'''(x_i) \neq 0$ (i = 1, ..., n - 1), using the same method as above we can get $nHd_n^{-\frac{1}{n+2}} = 0$ and so H = 0. Thus continuing such process we can get

$$G_2'' = d_2, \ldots, \ G_n'' = d_n$$

and

$$nH = (d_2 \dots d_n)^{\frac{1}{n+2}} Q_1(x_1)$$

i.e.

$$nH = (d_2 \dots d_n)^{\frac{1}{n+2}} \varepsilon_1 G_1^{'' - \frac{3n+5}{n+2}} \left(-\frac{2n+3}{(n+2)^2} G_1^{''' 2} + \frac{1}{n+2} G_1^{''} G_1^{(4)} \right), \quad (3.9)$$

where d_2, \ldots, d_n are constant and $G_1^{\prime\prime\prime} \neq 0$ so that $H \neq 0$. This completes the proof of Lemma.

Now we begin the proof of Theorem. Affine minimal translation hypersurfaces, that is the case H = 0 are classified in [7], [11]. Then by Lemma, we only need to treat with the case that $G_2''' = \cdots = G_n''' = 0$ and $G_1'' \neq 0$. Hence from (3.9) we get

$$HCG_{1}^{''3-\frac{1}{n+2}} = -\frac{2n+3}{n+2}G_{1}^{'''2} + G_{1}^{''}G_{1}^{(4)},$$
(3.10)

where

$$C = n(n+2)\varepsilon_1(d_2\dots d_n)^{-\frac{1}{n+2}}.$$

Let $g(x_1) = G''_1(x_1)$ and s = g'. Then from (3.10) we have

$$g'' - \frac{2n+3}{n+2}\frac{1}{g}g'^2 = CHg^{\frac{2n+3}{n+2}}$$

and so

$$\frac{ds^2}{dg} - \frac{2(2n+3)}{n+2}\frac{1}{g}s^2 = 2CHg^{\frac{2n+3}{n+2}}.$$
(3.11)

Thus we get

$$s^{2} = g^{\frac{2(2n+3)}{n+2}} \left(-\frac{2(n+2)}{n+1} CHg^{-\frac{n+1}{n+2}} + d \right),$$

where d is a constant. Then we have

$$g' = s = \pm g^{\frac{2n+3}{n+2}} \left(-\frac{2(n+2)}{n+1} CHg^{-\frac{n+1}{n+2}} + d \right)^{\frac{1}{2}}.$$

Let $g^{-\frac{n+1}{n+2}} = m$. Then

$$\pm \frac{n+1}{n+2}(am+d)^{\frac{1}{2}}dx_1 = dm, \qquad (3.12)$$

where $a = -\frac{2(n+2)}{n+1}CH$. From (3.12) we get

$$\frac{2}{a}(am+d)^{\frac{1}{2}} = \pm \frac{n+1}{n+2}x_1 + e$$

and

$$g = m^{-\frac{n+2}{n+1}} = \left[\frac{a}{4}\left(\frac{n+1}{n+2}x_1 \pm e\right)^2 - \frac{d}{a}\right]^{-\frac{n+2}{n+1}},$$

i.e.

$$g = \left[-\frac{n+2}{2(n+1)} CH\left(\frac{n+1}{n+2}x_1 \pm e\right)^2 + \frac{(n+1)d}{2(n+2)CH} \right]^{-\frac{n+2}{n+1}}, \quad (3.13)$$

where e is a constant. So we get

$$G_{1}(x_{1}) = \int_{x_{0}}^{x_{1}} \left\{ \int_{t_{0}}^{t} \left[AH\left(\frac{n+1}{n+2}s \pm B\right)^{2} + a_{1} \right]^{-\frac{n+2}{n+1}} ds \right\} dt$$
$$= \left[A\left(\frac{n+1}{n+2}\right)^{2} \right]^{-\frac{n+2}{n+1}} \int_{x_{0}}^{x_{1}} \left\{ \int_{t_{0}}^{t} \left(Hs^{2} + a_{1}\right)^{-\frac{n+2}{n+1}} ds \right\} dt,$$

where

$$A = -\frac{(n+2)C}{2(n+1)}, \quad B = e, \quad a_1 = \frac{(n+1)d}{2(n+2)CH}$$

Therefore, under equiaffine translation we get

$$x_{n+1} = \alpha \int_{x_0}^{x_1} \left\{ \int_{t_0}^t \left(Hs^2 + a_1 \right)^{-\frac{n+2}{n+1}} ds \right\} dt + a_2 x_2^2 + \dots + a_n x_n^2, \quad (3.14)$$

where α, a_2, \ldots, a_n are constant.

This completes the proof of Theorem.

In particular, taking $a_1 = 0$ from (3.14) we get

$$x_{n+1} = A_1(x_1 + B_1)^{-\frac{2}{n+1}} + A_2x_1 + B_2 + a_2x_2^2 + \dots + a_nx_n^2, \quad (3.15)$$

where A_i , B_i , a_i are constant.

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