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# On generalized metric spaces and their associated Finsler spaces I. Fundamental relations 

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Dedicated to Professor Lajos Tamássy on his 70th birthday

## §0. Introduction

In a previous paper [3], we have investigated a generalized metric space $M_{n}=\left(M_{T}, g_{i j}(x, y)\right)$. Here let us consider the Finsler space $F_{n}^{*}(g)=$ $\left(M_{T}, F(x, y)\right)$ associated with $M_{n}$, where its Finsler metric is given by $F(x, y):=\sqrt{g_{i j} y^{i} y^{j}}$.

It is noticed that the metric tensor $g_{i j}(x, y)$ used here is positively homogeneous of degree 0 in $y$. Sometimes a generalized metric space $M_{n}=\left(M_{T}, g_{i j}(x, y)\right)$ was considered under the supposition that the metric $g_{i j}$ is (a) p-homogeneous, (b) non-homogeneous and (c) irrespective of homogeneity. On the other hand, H. Rund [9] showed, in his book: The Hamilton-Jacobi theory in the calculus of variations, that the case (a) corresponds to Metric Differential Geometry and Relativistic Mechanics and (b) to Geometrical Optics and Non-relativistic Mechanics. So, in the sequel, we shall call $M_{n}$, for (a) a generalized metric space ([3], [4], [5], [15]), (b) a generalized Lagrange space ([7]) and (c) a generalized Finsler space ([1], [2], [6], [12], [13], [14]).

The geometry of a generalized metric space $M_{n}$ is closely related to that of $F_{n}^{*}(g)$. However, its geometry is in contrast with that of (ordinary) Finsler space $F_{n}:=\left(M_{T}, F(x, y)\right)$. That is, there exist two characteristic tensors $C_{i j}$ and $P^{i}{ }_{j}$. For a given metric tensor $g_{i j}$ in $M_{n}$, the metric tensor $g^{*}{ }_{i j}$ of its associated Finsler space $F_{n}^{*}(g)$ is related as

$$
\begin{equation*}
g^{*}{ }_{i j}=g_{i j}+C_{i j}, \quad C_{i j}:=y^{h} \dot{\partial}_{j} g_{i h} \quad([3],(2.8)(b)) \tag{0.1}
\end{equation*}
$$

where the tensor $C_{i j}$ satisfies $C_{i j}=C_{i}{ }^{0}{ }_{j}$ and $C_{i j}=C_{j i}([3],(2.9))$. Vanishing of the tensor $C_{i j}$ means that the $M_{n}$ itself reduces to a Finsler space.

To determine the non-linear connection $N$, we assume that geodesics in $M_{n}$ are coincident with those in $F_{n}^{*}(g)$, that is,
(A0) $\quad 2 G^{i}=N_{j}^{i} y^{j}$.
Therefore another characteristic tensor $P^{i}{ }_{k}$ satisfies the following relations:

$$
\begin{equation*}
N_{k}^{i}=G_{k}^{i}-P_{k}^{i}, \quad P_{0}^{i}=0, \quad C_{i j / 0}=2 g^{*}{ }_{i h} P_{j}^{h}, \quad([3],(2.16)(f)), \tag{0.2}
\end{equation*}
$$

where $G_{j}^{i}$ is a unique non-linear connection of $F_{n}^{*}(g)$ and $N_{k}^{i}$ is an arbitrary non-linear connection in $M_{n}$. (0.2) shows that the arbitrary tensor $P^{i}{ }_{k}$ has disappeared in Finsler geometry. The fact that some differential equation does not contain the tensor $P^{i}{ }_{j}$ explicitly, implies that the geometrical property described by this equation is free from any choice of the nonlinear connection.

However, examples of a generalized metric space are very few. Let us consider the following metric in an $M_{n}$ :

$$
\begin{equation*}
g_{i j}(x, y)=a_{i j}(x)-\alpha(x, y) h_{i j}(x, y), \quad C_{i j}=\alpha h_{i j} \quad(\mathrm{cf.}[5]) \tag{0.3}
\end{equation*}
$$

where the tensor $a_{i j}(x)$ is a Riemannian metric. This metric defines a generalized metric space $M_{n}$ which is not a Finsler space and its associated Finsler space is a Riemannian space (cf. §3).

It is well known that in a Finsler space $F_{n}^{*}(g)$ we can define three types of connection: $\left[C^{*}\right],\left[R^{*}\right]$ and $\left[B^{*}\right]$ (cf. §2) in a natural way. On the other hand, in a space $M_{n}([3])$ we defined three types of connection: $[C],[R]$ and $[B]$ (cf. §1). However, the connection $[B]$ in $M_{n}$ and the connection $\left[B^{*}\right]$ in $F_{n}^{*}(g)$ are coincident. In a same underlying space $M_{T}$, we can consider five connections: $[C],[R],[B],\left[C^{*}\right]$ and $\left[R^{*}\right]$ originating from only one structure: the metric tensor $g_{i j}(x, y)$.

One of the purposes of the present paper is to find the relations between $[C]$ in a space $M_{n}$ and $\left[C^{*}\right]$ in a space $F_{n}^{*}(g)$. In virtue of these equations, the properties of $M_{n}$ are investigated by means of well-known theorems in a Finsler space $F_{n}^{*}(g)$, which suggest some properties in $M_{n}$. As we see, the tensor $C_{i j}$ holds a key to investigate the geometry of spaces $M_{n}$. Especially, the most important fact is that the connection parameters $F_{j}{ }^{i}{ }_{k}$ of $[C]$ and ${ }^{*} \Gamma_{j}{ }^{i}{ }_{k}$ of $\left[C^{*}\right]$ are coincident if and only if $C_{i j / k}=0$ (Theorem 2.4).

Roughly speaking, if a generalized metric space $M_{n}$ itself is a Finsler-, a Riemannian- or a $g$-Minkowski space, then its associated Finsler space $F_{n}^{*}(g)$ preserves this property. Our interest is in the inverse problem.
$\S 1$ is the summary of results obtained in $M_{n} . \S 2$ is devoted to deriving the relations between $[C]$ and $\left[C^{*}\right]$ in terms of the tensors in $M_{n}$. In $\S \S 3$, 4, we investigate a generalized metric space whose associated Finsler space is a Riemannian or a Minkowski space. We shall show that
[A] If an $R M_{n}$ space satisfies the condition $C_{i j / k}=0$, then the space $M_{n}$ is a $g$-Berwald space (Theorem 3.7).
[B] A necessary and sufficient condition for a space $M_{n}$ to be a $g$-Minkowski space is that the curvature tensors $K_{h}{ }^{i}{ }_{j k}$ and $F_{h}{ }^{i}{ }_{j k}$ vanish (Theorem 4.1).
[C] A necessary and sufficient condition for a space $M_{n}$ to be an $M M_{n}$ space is that the curvature tensors $H_{h}{ }^{i}{ }_{j k}$ and $G_{h}{ }^{i}{ }_{j k}$ vanish (Theorem 4.2). [D] If an $M M_{n}$ space satisfies the condition $C_{i j / k}=0$, then the space is a $g$-Minkowski space (Theorem 4.4).

We raise or lower the indices by means of $g_{i j}$ only without comment.

## $\S$ 1. Preliminaries in $M_{n}$

The purpose of this section is to summarize the connections in $M_{n}$.

### 1.1. Assumptions on the metric tensor $g_{i j}(x, y)$.

Let $M$ be an $n$-dimensional manifold of class $C^{\infty}$ with local coordinates $\left(x^{i}\right)$ and $T(M)$ its tangent vector bundle with local coordinates $\left(x^{i}, y^{i}\right)$. Let us denote by $M_{T}$ a manifold of non-vanishing tangent vectors: $M_{T}:=T(M)-\{0\}$. A generalized metric space is a pair $M_{n}=\left(M_{T}, g_{i j}(x, y)\right)$, where the metric tensor $g_{i j}$ satisfies the following conditions:
(A1) $g_{i j}(x, y)$ is positively homogeneous of degree 0 in $y$,
(A2) $g_{i j} X^{i} X^{j}$ is positive definite,
(A3) $g^{*}{ }_{i j}:=\frac{1}{2} \dot{\partial}_{i} \dot{\partial}_{j} F^{2}$ is non-degenerate, where $F(x, y)=\sqrt{g_{i j} y^{i} y^{j}}$ and $\dot{\partial}_{j}:=\partial / \partial y^{j}$.
From conditions (A2) and (A3) a pair $F_{n}^{*}(g)=\left(M_{T}, F(x, y)\right)$ is a Finsler space (called the associated Finsler space of $M_{n}$ ). In [3], we introduced the following three types of connection:
$[C]$ the metrical connection $C \Gamma(N): \omega_{j}^{i}=F_{j}{ }^{i}{ }_{k} d x^{k}+C_{j}{ }^{i}{ }_{k} \delta y^{k} ; \delta y^{k}=d y^{k}+$ $N_{h}^{k} d x^{h}$ such that $\delta g_{i j}=d g_{i j}-\omega_{i}^{h} g_{h j}-\omega_{j}^{h} g_{i h}=g_{i j / k} d x^{k}+g_{i j /(k)} \delta y^{k}=0$, where

$$
\begin{array}{ll}
g_{i j / k}:=d_{k} g_{i j}-F_{i}{ }^{h}{ }_{k} g_{h j}-F_{j}{ }^{h}{ }_{k} g_{i h}=0, & d_{k}:=\partial_{k}-N_{k}^{r} \dot{\partial}_{r}, \\
g_{i j /(k)}:=g_{i j(k)}-C_{i}{ }^{h}{ }_{k} g_{h j}-C_{j}{ }^{h}{ }_{k} g_{i h}=0, & g_{i j(k)}:=\dot{\partial}_{k} g_{i j},
\end{array}
$$

and satisfies the following conditions:
(A4)
(a) $N_{k}^{i}=F_{j}{ }^{i}{ }_{k} y^{j}$,
(b) $F_{j}{ }^{i}{ }_{k}=F_{k}{ }^{i}{ }_{j}$,
(c) $C_{j}{ }^{i}{ }_{k}=C_{k}{ }^{i}{ }_{j}$.
$[R]$ the $h$-metrical connection $R \Gamma(N): \omega_{j}^{i}=F_{j}{ }^{i}{ }_{k} d x^{k}$ so that $g_{i j / k}=0$.
$[B]$ the non-metrical connection $B \Gamma(G): \omega_{j}^{i}=G_{j}{ }^{i}{ }_{k} d x^{k} ; \quad G_{j}{ }^{i}{ }_{k}:=\dot{\partial}_{k} G_{j}^{i}$, where

$$
\begin{aligned}
G_{j}^{i} & :=\dot{\partial}_{j} G^{i}, \quad 4 G^{i}:=g^{* i h}\left(y^{j} \partial_{j} \dot{\partial}_{h} F^{2}-\partial_{h} F^{2}\right), \\
\partial_{h} & =\partial / \partial x^{h}, \quad g^{* i h} g^{*}{ }_{h j}=\delta_{j}^{i} .
\end{aligned}
$$

It is evident that $[B]$ in $M_{n}$ is coincident with $\left[B^{*}\right]$ in $F_{n}^{*}(g)$. However, the general non-linear connection $N_{j}^{i}$ of $[C]$ satisfies (A0) $N_{j}^{i} y^{j}=2 G^{i}$ implicitly. So differentiating this equation, we have

$$
\begin{equation*}
N_{j}^{i}=G_{j}^{i}-P_{j}^{i}, \quad P_{j}^{i}:=\frac{1}{2}\left(y^{h} \dot{\partial}_{j} N_{h}^{i}-N_{j}^{i}\right), \quad P_{0}^{i}:=P^{i}{ }_{j} y^{j}=0, \tag{1.1}
\end{equation*}
$$

where the index 0 means the transvection with $y$.
The conditions (A1) and (A4)(c) give
(a) $g^{*}{ }_{i j}=g_{i j}+C_{i j}, \quad C_{i j}:=y^{h} \dot{\partial}_{j} g_{i h}=C_{j i} \quad([3],(2.8))$,
(b) $C_{0}{ }^{i}{ }_{k}=C_{j}{ }^{i}{ }_{0}=0$,
(c) $\quad C_{0}{ }^{0}{ }_{k}=\frac{1}{2} g_{h j(k)} y^{h} y^{j}=0$
$([3],(2.3),(2.6))$.
The connection parameters for $C \Gamma(N)$ are given by

$$
\begin{align*}
F_{j}{ }^{i}{ }_{k} & =\frac{1}{2} g^{i h}\left(d_{k} g_{h j}+d_{j} g_{h k}-d_{h} g_{j k}\right), \\
C_{j}{ }^{i}{ }_{k} & =\frac{1}{2} g^{i h}\left(g_{h j(k)}+g_{h k(j)}-g_{j k(h)}\right), \quad C_{i}{ }^{0}{ }_{j}=C_{i j} . \tag{1.3}
\end{align*}
$$

Then we have

$$
\begin{align*}
& \text { (a) } y_{j}=g_{i j} y^{i}=g^{*}{ }_{i j} y^{i}, \quad y^{i}=g^{* i h} y_{h}, \quad y^{i}{ }_{(j)}=y^{i} /(j)=\delta_{j}^{i},  \tag{1.4}\\
& \text { (b) } y_{i(j)}=g^{*}{ }_{i j}, \quad y_{i /(j)}=g_{i j}, \quad y_{i / j}=0 .
\end{align*}
$$

Remark. The homogeneous condition (A1) implies that if there exists a coordinate system such that the metric $g_{i j}$ is expressed by $g_{i j}=$ $e^{2 \sigma(x, y)} a_{i j}(x)([6],[14])$, then the metric itself is Riemannian. In fact, because the scalar $\sigma(x, y)$ must be $p$-homogeneous of degree 0 in $y$, the relation $C_{i j}=C_{j i}$ gives $y_{i} \sigma_{(j)}=y_{j} \sigma_{(i)}$. This means $\sigma_{(i)}=0$.

### 1.2. The curvature and torsion tensors.

For curvature and torsion forms, we defined in [3] as follows:

$$
\begin{align*}
& \text { (a) } \Omega_{j}^{i}:=\left[d \omega_{j}^{i}\right]+\left[\omega_{h}^{i} \omega_{j}^{h}\right] \\
& \text { (b) } \Omega^{(i)}:=\left[\delta \delta y^{i}\right]=\left[d \delta y^{i}\right]+\left[\omega_{h}^{i} \delta y^{h}\right]=\Omega_{0}^{i},  \tag{1.5}\\
& \text { (c) } \Omega^{i}:=\left[\delta d x^{i}\right]=\left[d d x^{i}\right]+\left[\omega_{h}^{i} d x^{h}\right] .
\end{align*}
$$

We shall denote

$$
\begin{aligned}
{[C] \quad C \Gamma(N): } & \Omega_{j}^{i}=-\frac{1}{2} R_{j}{ }^{i}{ }_{k l}[k, l]-P_{j}{ }^{i}{ }_{k l}[k,(l)]-\frac{1}{2} S_{j}{ }^{i}{ }_{k l}[(k),(l)], \\
& \Omega^{(i)}=-\frac{1}{2} R^{i}{ }_{k l}[k, l]-P^{i}{ }_{k l}[k,(l)], \quad \Omega^{i}=-C_{j}{ }^{i}{ }_{k}[j,(k)] ; \\
{[R] \quad R \Gamma(N): } & \Omega_{j}^{i}=-\frac{1}{2} K_{j}{ }^{i}{ }_{k l}[k, l]-F_{j}{ }^{i}{ }_{k l}[k,(l)], \\
& \Omega^{(i)}=-\frac{1}{2} R^{i}{ }_{k l}[k, l]-P^{i}{ }_{k l}[k,(l)], \quad \Omega^{i}=0 ; \\
{[B] \quad B \Gamma(G): } & \Omega_{j}^{i}=-\frac{1}{2} H_{j}{ }^{i}{ }_{k l}[k, l]-G_{j}{ }^{i}{ }_{k l}\left[k,(l)^{*}\right] \\
& \Omega^{(i)}=-\frac{1}{2} H^{i}{ }_{k l}[k, l], \quad \Omega^{i}=0
\end{aligned}
$$

where $[k, l]:=\left[d x^{k}, d x^{l}\right],[k,(l)]:=\left[d x^{k}, \delta y^{l}\right],[(k),(l)]:=\left[\delta y^{k}, \delta y^{l}\right]$ and $\left[k,(l)^{*}\right]:=\left[d x^{k}, \delta^{*} y^{l}\right]=\left[d x^{k}, \delta y^{l}+P^{l}{ }_{h} d x^{h}\right]=[k,(l)]+P^{l}{ }_{h}[k, h]$.

The covariant derivatives for a vector $v^{i}(x, y)$ with respect to $x^{k}$ and $y^{k}$ are defined as follows:

$$
\begin{array}{rlrl}
v^{i} / k:=d_{k} v^{i}+F_{j}{ }^{i}{ }_{k} v^{j}, & v^{i}{ }_{/(k)}:=v^{i}{ }_{(k)}+C_{j}{ }^{i}{ }_{k} v^{j} & & \text { for }[\mathrm{C}],[\mathrm{R}], \\
v^{i}{ }_{/ / k}:=\bar{d}_{k} v^{i}+G_{j}{ }^{i}{ }_{k} v^{j}, & v^{i}{ }_{(k)}:=\dot{\partial}_{k} v^{i} & \text { for }[\mathrm{B}],
\end{array}
$$

where $\bar{d}_{k}:=\partial_{k}-G_{k}^{h} \dot{\partial}_{h}=d_{k}-P^{h}{ }_{k} \dot{\partial}_{h}$.
We shall list the identities for curvature and torsion tensors in $M_{n}$ :
(a) $C_{0 j}=C_{i 0}=0$, $P_{0}^{i}=P_{k}^{0}=0$,
(b) $g_{i j(k)}=C_{i j k}+C_{j i k}$,
(c) $P^{i}{ }_{0 k}=2 P^{i}{ }_{k}$
([3], Proposition 2.6),
(a) $R_{h}{ }^{i}{ }_{j k}=K_{h}{ }^{i}{ }_{j k}+C_{h}{ }^{i}{ }_{r} R^{r}{ }_{j k}, \quad F_{h}{ }^{i}{ }_{j k}:=\dot{\partial}_{k} F_{h}{ }^{i}{ }_{j}$, $P_{h}{ }^{i}{ }_{j k}=F_{h}{ }^{i}{ }_{j k}-C_{h}{ }^{i}{ }_{k / j}+C_{h}{ }^{i}{ }_{m} P^{m}{ }_{j k}, \quad P^{i}{ }_{j k}=N_{j(k)}^{i}-F_{k}{ }^{i}{ }_{j}$,
(b) $R_{0}{ }^{i}{ }_{j k}=K_{0}{ }^{i}{ }_{j k}=R^{i}{ }_{j k}, \quad H_{0}{ }^{i}{ }_{j k}=H^{i}{ }_{j k}$, $P_{0}{ }^{i}{ }_{j k}=F_{0}{ }^{i}{ }_{j k}=F_{j}{ }^{i}{ }_{0 k}=P^{i}{ }_{j k}, \quad S_{0}{ }^{i}{ }_{j k}=0$,
(c) $\quad R^{0}{ }_{j k}=0, \quad P^{0}{ }_{j k}=0, \quad P^{i}{ }_{j 0}=0, \quad H^{0}{ }_{j k}=0$,
(d) $\quad R_{h}{ }^{0}{ }_{j k}=-g_{h r} R^{r}{ }_{j k}, \quad K_{h}{ }^{0}{ }_{j k}=-g^{*}{ }_{h r} R^{r}{ }_{j k}$, $H_{h}{ }^{0}{ }_{j k}=-g^{*}{ }_{h r} H^{r}{ }_{j k}, \quad F_{h}{ }^{0}{ }_{j k}=C_{h k / j}-g^{*}{ }_{h r} P^{r}{ }_{j k}$, $S_{h}{ }^{0}{ }_{j k}=C_{h j(k)}+C_{h j k}-j \mid k=0$,
(a) $\quad R_{h i j k}+R_{i h j k}=0, \quad P_{h i j k}+P_{i h j k}=0, \quad S_{h i j k}+S_{i h j k}=0$,
(b) $K_{h i j k}+K_{i h j k}=-g_{h i(r)} R^{r}{ }_{j k}$,
(c) $F_{h i j k}+F_{i h j k}=g_{h i(k) / j}-g_{h i(r)} P^{r}{ }_{j k}$,
(a) $C_{h j / k}-C_{h k / j}=g^{*}{ }_{j r} P^{r}{ }_{k h}-g^{*}{ }_{k r} P^{r}{ }_{j h}$,
(b) $g_{h i(k) / 0}=g_{i r} P^{r}{ }_{h k}+g_{h r} P^{r}{ }_{i k}+2 g_{h i(r)} P^{r}{ }_{k}$,
(c) $C_{j k / 0}=2 g^{*}{ }_{j r} P^{r}{ }_{k}=g^{*}{ }_{j r} P^{r}{ }_{k}+g^{*}{ }_{k r} P^{r}{ }_{j}$,
(a) $H^{i}{ }_{j k(h)}=H_{h}{ }^{i}{ }_{j k}$,
(b) $H^{i}{ }_{k(j)}-j \mid k=3 H^{i}{ }_{j k}, \quad H^{i}{ }_{k}:=H^{i}{ }_{0 k}$,
(c) $\quad H_{h j}:=H_{h}{ }^{i}{ }_{j i}=H_{j(h)}, \quad H_{j}:=H^{i}{ }_{j i}$,
where $j \mid k$ means the interchange of the indices $j, k$ in the foregoing terms.
1.3. Relations between [ $C$ ] and [ $B$ ]; Difference tensor $D_{j}{ }^{i}{ }_{k}$.

It is easily seen that for a vector $v^{i}$ we find
$v^{i}{ }_{/ / k}=\bar{d}_{k} v^{i}+G_{h}{ }^{i}{ }_{k} v^{h}=v^{i}{ }_{/ k}+D_{h}{ }^{i}{ }_{k} v^{h}-P^{h}{ }_{k} v^{i}{ }_{(h)}, \quad D_{h}{ }^{i}{ }_{k}:=G_{h}{ }^{i}{ }_{k}-F_{h}{ }^{i}{ }_{k}$.
Hence we have for the metric tensor $g_{i j}$
(a) $g_{i j / / k}=-D_{i}{ }^{h}{ }_{k} g_{h j}-D_{j}{ }^{h}{ }_{k} g_{i h}-P^{h}{ }_{k} g_{i j(h)}$,
(b) $-2 D_{j}{ }^{i}{ }_{k}=g^{i h}\left(g_{h j / / k}+g_{h k / / j}-g_{j k / / h}+g_{h j(r)} P^{r}{ }_{k}\right.$ $\left.+g_{h k(r)} P^{r}{ }_{j}-g_{j k(r)} P^{r}{ }_{h}\right)$,
(c) $g_{i j / / 0}=-g_{i h} P^{h}{ }_{j}-g_{j h} P^{h}{ }_{i}$.

Proposition 1.1 ([3], Proposition 3.1). The difference tensor $D_{j}{ }^{i}{ }_{k}$ is expressed by

$$
\begin{equation*}
D_{j}{ }^{i}{ }_{k}=P_{j k}^{i}+P_{j(k)}^{i}=D_{k}{ }_{j}{ }_{j}, \tag{1.13}
\end{equation*}
$$

and satisfies the following relations:

$$
\begin{align*}
& \text { (a) } D_{0}{ }^{i}{ }_{k}=P^{i}{ }_{k}, \quad \text { (b) } \quad D_{j}{ }^{0}{ }_{k}=-g^{*}{ }_{j h} P^{h}{ }_{k},  \tag{1.14}\\
& \text { (c) } D_{j}{ }^{i}{ }_{k(l)}=G_{j}{ }^{i}{ }_{k l}-F_{j}{ }^{i}{ }_{k l}, \quad \text { (d) } \quad D_{j}{ }^{i}{ }_{k(l)} y^{j}=-P_{k l}^{i} .
\end{align*}
$$

The following relations are known:

$$
\begin{equation*}
y^{i} / / k=0, \quad y_{j / / k}=0 \tag{1.15}
\end{equation*}
$$

(a) $H_{h i j k}+H_{i h j k}=-g_{h i / / j / / k}+g_{h i / / k / / j}-g_{h i(r)} H^{r}{ }_{j k}$,
(b) $G_{h}{ }^{0}{ }_{j k}=g^{*}{ }_{h j / / k}=g_{h j / / k}+C_{h j / / k}$,
(c) $\quad G_{h i j k}+G_{i h j k}=-g_{h i / / j(k)}+g_{h i(k) / / j}$,
(a) $H_{h}{ }^{i}{ }_{j k}=K_{h}{ }^{i}{ }_{j k}+E_{h}{ }^{i}{ }_{j k}$,

$$
\begin{equation*}
E_{h}{ }^{i}{ }_{j k}:=D_{h}{ }^{i}{ }_{j / k}+D_{h}{ }^{r}{ }_{j} D_{r}{ }^{i}{ }_{k}-G_{h}{ }^{i}{ }_{j r} P^{r}{ }_{k}-j \mid k, \tag{1.17}
\end{equation*}
$$

(b) $\quad E^{i}{ }_{j k}:=E_{0}{ }^{i}{ }_{j k}=H^{i}{ }_{j k}-R^{i}{ }_{j k}=P^{i}{ }_{j / k}+P^{r}{ }_{j} D_{r}{ }^{i}{ }_{k}-j \mid k$.

### 1.4. Projection to the indicatrix.

Let us denote by $\mathrm{p} \cdot T$ the projection of a tensor $T$ to the indicatrix, e.g., for a tensor $T^{i}{ }_{j}$, we shall define $\mathrm{p} \cdot T^{i}{ }_{j}:=h_{a}^{i} T^{a}{ }_{b} h_{j}^{b}$. If $\mathrm{p} \cdot T=T$ holds, then the tensor $T$ is called an indicatric tensor. For example, as the torsion vector $C_{j}:=C_{j}{ }^{k}{ }_{k}$ is $p$-homogeneous of degree -1 , we find

$$
\begin{equation*}
F \mathrm{p} \cdot C_{j /(k)}=F h_{j}^{a} h_{k}^{b} C_{a /(b)}=F C_{j /(k)}+l_{j} C_{k}+l_{k} C_{j} \tag{1.18}
\end{equation*}
$$

Proposition 1.2 (cf. [10], (3.18)). Let $K(x, y)$ be a scalar, p-homogeneous of degree 0 in $y$, and put $K_{j}:=F K_{(j)}, K_{j k}=K_{k j}:=F \mathrm{p} \cdot K_{j(k)}$ and $K_{h j k}:=F \mathrm{p} \cdot K_{j k(h)}$. Then we have

$$
\begin{equation*}
K_{h j k}+K_{h} h_{j k}^{*}-h \mid j=0, \quad h^{*}{ }_{j k}=h_{j k}+C_{j k} \tag{1.19}
\end{equation*}
$$

Therefore the scalar $K$ is independent of $y$ if $K_{j}=0$ or $K_{j k}=0$ holds.

## $\S 2$. The associated Finsler space $F_{n}^{*}(g)$ of $M_{n}$

In this section, we shall find the relations in which the connections and curvature and torsion tensors of $F_{n}^{*}(g)$ are expressed in terms of $M_{n}$.

### 2.1. Connection parameters of $\left[C^{*}\right]$ and $[C]$.

As usual, we can define the connections in $F_{n}^{*}(g)$.
$\left[C^{*}\right]$ the metrical connection $C F^{*}(G): \omega^{* i}{ }_{j}:={ }^{*} \Gamma_{j}{ }^{i}{ }_{k} d x^{k}+C^{*}{ }_{j}{ }^{i}{ }_{k} \delta^{*} y^{k}$,
$\delta^{*} y^{k}:=\delta y^{k}+P^{k}{ }_{h} d x^{h}$ such that $\delta^{*} g^{*}{ }_{i j}=0$,
${ }^{*} \Gamma_{j}{ }^{i}{ }_{k}={ }^{*} \Gamma_{k}{ }_{k}{ }_{j}, \quad C^{*}{ }_{j}{ }^{i}{ }_{k}=\frac{1}{2} g^{* i h} g^{*}{ }_{h j}(k)$.
[ $R^{*}$ ] the $h$-metrical connection $R F^{*}(G): \omega_{j}^{* i}:={ }^{*} \Gamma_{j}{ }^{i}{ }_{k} d x^{k}, \quad g^{*}{ }_{i j}{ }^{*} k=0$.
Let us put

$$
\omega^{* i}{ }_{j}=\omega_{j}^{i}+t_{j}^{i}, \quad t_{j}^{i}:=A_{j}{ }^{i}{ }_{k} d x^{k}+B_{j}{ }^{i}{ }_{k} \delta y^{k} .
$$

Accordingly we have

$$
\begin{equation*}
\text { (a) }{ }^{*} \Gamma_{j}{ }^{i}{ }_{k}=F_{j}{ }^{i}{ }_{k}+A_{j}{ }^{i}{ }_{k}-C^{*}{ }_{j}{ }^{i}{ }_{h} P^{h}{ }_{k}, \quad \text { (b) } \quad C^{*}{ }_{j}{ }^{i}{ }_{k}=C_{j}{ }^{i}{ }_{k}+B_{j}{ }^{i}{ }_{k}, \tag{2.1}
\end{equation*}
$$

and using the symmetric property of ${ }^{*} \Gamma_{j}{ }^{i}{ }_{k}, F_{j}{ }^{i} k, C^{*}{ }_{j}{ }^{i}{ }_{k}$ and $C_{j}{ }^{i}{ }_{k}$, we see

$$
\begin{align*}
& A_{j}{ }^{i}{ }_{k}+A_{k}{ }^{i}{ }_{j}=2\left({ }^{*} \Gamma_{j}{ }^{i}{ }_{k}-F_{j}{ }^{i}{ }_{k}\right)+C^{*}{ }_{j}{ }^{i}{ }_{h} P^{h}{ }_{k}+C^{*}{ }_{k}{ }^{i}{ }_{h} P^{h}{ }_{j},  \tag{2.2}\\
& A_{j}{ }^{i}{ }_{k}-A_{k}{ }^{i}{ }_{j}=C^{*}{ }_{j}{ }^{i}{ }_{h} P^{h}{ }_{k}-C^{*}{ }_{k}{ }^{i}{ }_{h} P^{h}{ }_{j}, \quad B_{j}{ }^{i}{ }_{k}=B_{k}{ }^{i}{ }_{j} .
\end{align*}
$$

To determine the tensors $A_{j}{ }^{i}{ }_{k}$ and $B_{j}{ }^{i}{ }_{k}$, we give
Lemma 2.1. The form $t_{j}^{i}$ satisfies the following relation:

$$
\begin{equation*}
\delta C_{i j}=t_{i}^{h} g^{*}{ }_{h j}+t_{j}^{h} g^{*}{ }_{h i} \tag{2.3}
\end{equation*}
$$

Proof. Because both connections are metrical, we see

$$
\begin{aligned}
0=\delta^{*} g^{*}{ }_{i j} & =d g^{*}{ }_{i j}-\omega_{i}^{*} g^{*}{ }_{h j}-\omega_{j}^{* h} g^{*}{ }_{h i} \\
& =d g_{i j}+d C_{i j}-\left(\omega_{i}^{h}+t_{i}^{h}\right)\left(g_{h j}+C_{h j}\right)-\left(\omega_{j}^{h}+t_{j}^{h}\right)\left(g_{h i}+C_{h i}\right) \\
& =\delta g_{i j}+\delta C_{i j}-t_{i}^{h} g^{*}{ }_{h j}-t_{j}^{h} g^{*}{ }_{h i} .
\end{aligned}
$$

Hence the condition $\delta g_{i j}=0$ gives (2.3).
From (2.3) we see

$$
\begin{equation*}
C_{i j / k}=A_{i}{ }_{k}{ }_{k} g^{*}{ }_{h j}+{A_{j}}^{h}{ }_{k} g^{*}{ }_{h i}, \quad C_{i j /(k)}={B_{i}}^{h}{ }_{k} g^{*}{ }_{h j}+B_{j}{ }^{h}{ }_{k} g^{*}{ }_{h i} \tag{2.4}
\end{equation*}
$$

Now, applying the Christoffel process to (2.4) and using (2.2), we obtain

Proposition 2.2. Two tensors $A_{j}{ }^{i}{ }_{k}$ and $B_{j}{ }^{i}{ }_{k}$ are given by
(a) $\quad A_{j}{ }^{i}{ }_{k}=\frac{1}{2} g^{* i h}\left(C_{h j / k}+C_{h k / j}-C_{j k / h}\right)-C^{*}{ }_{k}{ }^{i}{ }_{r} P^{r}{ }_{j}+g^{* i h} C^{*}{ }_{j k r} P^{r}{ }_{h}$,
(b) $\quad B_{j}{ }^{i}{ }_{k}=\frac{1}{2} g^{* i h}\left(C_{h j /(k)}+C_{h k /(j)}-C_{j k /(h)}\right)$,
and satisfy the following relations:
(a) $A_{0}{ }^{i}{ }_{k}=A_{k}{ }^{i}{ }_{0}=P^{i}{ }_{k}, \quad A_{j}{ }^{0}{ }_{k}=-\frac{1}{2} C_{j k / 0}=-g^{*}{ }_{j h} P^{h}{ }_{k}$,
(b) $B_{0}{ }^{i}{ }_{k}=B_{k}{ }^{i}{ }_{0}=0, \quad B_{j}{ }^{0}{ }_{k}=-C_{j k}$,
(c) $\quad t_{0}^{i}=P_{k}^{i} d x^{k}$.

We shall prove
Proposition 2.3. In a generalized metric space, we have that
(a) $A_{j}{ }^{i}{ }_{k}=0$ is equivalent to $C_{i j / k}=0$,
(b) $B_{j}{ }^{i}{ }_{k}=0$ is equivalent to $C_{i j /(k)}=0$,
(c) $C_{i j /(k)}=0$ is equivalent to $C_{i j}=0$.

Proof. If $A_{j}{ }^{i}{ }_{k}=0$ or $B_{j}{ }^{i}{ }_{k}=0$, we have from (2.4) $C_{i j / k}=0$ or $C_{i j /(k)}=0$, respectively. The inverse of $(a)$ is obvious from (1.9)(c) and $(2.5)(a) .(b)$ and (c) are evident.

By means of $C_{j k / 0}=2 g^{*}{ }_{j r} P^{r}{ }_{k}$ and (2.5)(a), the relation (2.1)(a) shows the following

Theorem 2.4. A necessary and sufficient condition for the connection parameters $F_{j}{ }^{i}{ }_{k}$ of $[C]$ and ${ }^{*} \Gamma_{j}{ }^{i}{ }_{k}$ of $\left[C^{*}\right]$ to be coincident is that the condition $C_{i j / k}=0$ holds.

### 2.2. Curvature forms of $\left[C^{*}\right]$ and $[C]$.

Lemma 2.5. The curvature forms $\Omega^{* i}{ }_{j}$ of $C F^{*}(G)$ and $\Omega_{j}^{i}$ of $C \Gamma(N)$ are related as follows:

$$
\begin{equation*}
\Omega_{j}^{* i}=\Omega_{j}^{i}+\left[\delta t_{j}^{i}\right]+\left[t_{h}^{i} t_{j}^{h}\right] . \tag{2.7}
\end{equation*}
$$

Proof. From the definition and the relation $\omega^{*}=\omega+t$ (without indices), we see

$$
\begin{aligned}
\Omega^{*} & =\left[d \omega^{*}\right]+\left[\omega^{*} \omega^{*}\right]=[d \omega]+[d t]+[(\omega+t)(\omega+t)] \\
& =[d \omega]+[\omega \omega]+[d t]+[\omega t]+[t \omega]+[t t]=\Omega+[\delta t]+[t t],
\end{aligned}
$$

where we used the matrix product rule.
We remark that

$$
\begin{aligned}
& {[t \omega] }=\left[t_{h}^{i} \omega_{j}^{h}\right]=-\left[\omega_{j}^{h} t_{h}^{i}\right]=-[\omega t] \\
& {\left.\left[\delta t_{j}^{i}\right]:=\left[d t_{j}^{i}\right]+\left[\omega_{h}^{i} h_{j}^{h}\right]-\left[\omega_{j}^{h} t_{h}^{i}\right] \quad \text { (dor the 1-form } t_{j}^{i}\right), } \\
& \text { (definition). }
\end{aligned}
$$

As usual in a Finsler space $F_{n}^{*}(g)$, we put

$$
\Omega_{j}^{* i}=-\frac{1}{2} R^{*}{ }_{j}{ }^{i}{ }_{k l}[k, l]-P^{*}{ }_{j}{ }^{i}{ }_{k l}\left[k,(l)^{*}\right]-\frac{1}{2} S^{*}{ }_{j}{ }^{i}{ }_{k l}\left[(k)^{*},(l)^{*}\right],
$$

where $\left[(k)^{*},(l)^{*}\right]:=[(k),(l)]+P^{k}{ }_{r}[r,(l)]+P^{l}{ }_{r}[(k), r]+P^{k}{ }_{r} P^{l}{ }_{s}[r, s]$. Hence we get

$$
\begin{align*}
\Omega_{j}^{* i}=- & \frac{1}{2}\left(R_{j}^{*}{ }_{j}{ }_{k l}+P^{*}{ }_{j}{ }^{i}{ }_{k r} P^{r}{ }_{l}-P^{*}{ }_{j}{ }^{i}{ }_{l r} P^{r}{ }_{k}+S^{*}{ }_{j}{ }^{i}{ }_{r s} P^{r}{ }_{k} P^{s}{ }_{l}\right)[k, l]  \tag{2.8}\\
& -\left(P^{*}{ }_{j}{ }^{i}{ }_{k l}+S^{*}{ }_{j}{ }^{i}{ }_{r l} P^{r}{ }_{k}\right)[k,(l)]-\frac{1}{2} S^{*}{ }_{j}{ }^{k}{ }_{k l}[(k),(l)] .
\end{align*}
$$

Let us now carry out the following calculations:

$$
\begin{align*}
(a) \quad\left[\delta t_{j}^{i}\right]= & {\left[\delta\left(A_{j}{ }^{i}{ }_{k} d x^{k}+B_{j}{ }^{i}{ }_{k} \delta y^{k}\right)\right] } \\
= & {\left[\delta A_{j}{ }^{i}{ }_{k}, d x^{k}\right]+\left[\delta B_{j}{ }^{i}{ }_{k}, \delta y^{k}\right]+A_{j}{ }^{i}{ }_{h}\left[\delta d x^{h}\right]+B_{j}{ }^{i}{ }_{h}\left[\delta \delta y^{h}\right] } \\
= & -\frac{1}{2}\left(A_{j}{ }^{i}{ }_{k / l}-A_{j}{ }^{i}{ }_{l / k}+B_{j}{ }^{i}{ }_{h} R^{h}{ }_{k l}\right)[k, l] \\
& -\left(A_{j}{ }^{i}{ }_{k /(l)}-B_{j}{ }^{i}{ }_{l / k}+A_{j}{ }^{i}{ }_{h} C_{k}{ }^{h}{ }_{l}+B_{j}{ }^{i}{ }_{h} P^{h}{ }_{k l}\right)[k,(l)] \\
& -B_{j}{ }^{i}{ }_{k /(l)}[(k),(l)], \\
(b) \quad\left[t_{h}^{i} t_{j}^{h}\right]= & -A_{j}{ }^{h}{ }_{k} A_{h}{ }^{i}{ }^{l}[k, l]-\left(A_{j}{ }^{h}{ }_{k} B_{h}{ }^{i}{ }_{l}{ }_{l}-B_{j}{ }^{h}{ }_{l} A_{h}{ }^{i}{ }_{k}\right)[k,(l)]  \tag{b}\\
& -B_{j}{ }^{h}{ }_{k} B_{h}{ }^{i}{ }^{i}[(k),(l)],
\end{align*}
$$

where we used (1.5)(c) and (b). By means of (2.8) and (2.9), the relation (2.7) gives us the following

Proposition 2.6. In a space $M_{n}$, the curvature tensors of $C F^{*}(G)$ and $C \Gamma(N)$ are connected by the following relations:
(a) $R^{*}{ }_{j}{ }^{i}{ }_{k l}+P^{*}{ }_{j}{ }^{i}{ }_{k r} P^{r}{ }_{l}-P^{*}{ }_{j}{ }^{i}{ }_{l r} P^{r}{ }_{k}+S^{*}{ }_{j}{ }^{i}{ }_{r s} P^{r}{ }_{k} P^{s}{ }_{l}$

$$
=R_{j}{ }^{i}{ }_{k l}+B_{j}{ }^{i}{ }_{h} R^{h}{ }_{k l}+\left(A_{j}{ }^{i}{ }_{k / l}+A_{j}{ }^{h}{ }_{k} A_{h}{ }^{i}{ }_{l}-k \mid l\right),
$$

(b) $P^{*}{ }_{j}{ }^{i}{ }_{k l}+S^{*}{ }_{j}{ }_{j}{ }_{r l} P^{r}{ }_{k}$

$$
=P_{j}{ }^{i}{ }_{k l}+A_{j}{ }^{i}{ }_{k /(l)}-B_{j}{ }^{i}{ }_{l / k}+A_{j}{ }^{i}{ }_{h} C_{k}{ }^{h}{ }_{l}+B_{j}{ }^{i}{ }_{h} P^{h}{ }_{k l}
$$

$$
+A_{j}{ }^{h}{ }_{k} B_{h}{ }^{i}{ }_{l}-B_{j}{ }^{h}{ }_{l} A_{h}{ }^{i}{ }_{k},
$$

(c) $\quad S^{*}{ }_{j}{ }^{i}{ }_{k l}=S_{j}{ }^{i}{ }_{k l}+\left(B_{j}{ }^{i}{ }_{k /(l)}+B_{j}{ }^{h}{ }_{k} B_{h}{ }^{i}{ }_{l}-k \mid l\right)$.

### 2.3. Torsion forms of $\left[C^{*}\right]$ and $[C]$.

Lemma 2.7. The torsions $\Omega^{* i}, \Omega^{*(i)}$ of $C F^{*}(G)$ and $\Omega^{i}, \Omega^{(i)}$ of $C \Gamma(N)$ are related as follows:

$$
\begin{align*}
& \text { (a) } \Omega^{* i}=\Omega^{i}+\left[t_{j}^{i} d x^{j}\right]  \tag{2.11}\\
& \text { (b) } \Omega^{*(i)}=\Omega^{(i)}+\left[t_{j}^{i} \delta y^{j}\right]+\left[\delta t_{0}^{i}\right]+\left[t_{h}^{i} t_{0}^{h}\right],
\end{align*}
$$

where $\Omega^{* i}:=\left[\delta^{*} d x^{i}\right]$ and $\Omega^{*(i)}:=\left[\delta^{*} \delta^{*} y^{i}\right]=\Omega_{0}^{* i}$.
Proof. For ( $a$ ), we see

$$
\Omega^{* i}=\left[\delta^{*} d x^{i}\right]=\left[\delta d x^{i}\right]+\left[t_{j}^{i} d x^{j}\right]=\Omega^{i}+\left[t_{j}^{i} d x^{j}\right] .
$$

For (b), we see

$$
\begin{aligned}
\Omega^{*(i)} & =\left[\delta^{*} \delta^{*} y^{i}\right]=\left[\delta \delta^{*} y^{i}\right]+\left[t_{h}^{i} \delta^{*} y^{h}\right]=\left[\delta\left(\delta y^{i}+t_{0}^{i}\right)\right]+\left[t_{h}^{i}\left(\delta y^{h}+t_{0}^{h}\right)\right] \\
& =\Omega^{(i)}+\left[\delta t_{0}^{i}\right]+\left[t_{h}^{i} \delta y^{h}\right]+\left[t_{h}^{i} t_{0}^{h}\right] .
\end{aligned}
$$

Let us carry out the following calculations:

$$
\begin{aligned}
& \Omega^{* i}=-C^{*}{ }_{j}{ }_{k}{ }_{k}\left[j,(k)^{*}\right]=-C^{*}{ }_{j}{ }_{h}{ }_{2} P^{h}{ }_{k}[j, k]-C^{*}{ }_{j}{ }_{k}{ }_{k}[j,(k)], \\
& \Omega^{i}+\left[t_{j}^{i} d x^{j}\right]=-C_{j}{ }^{i}{ }_{k}[j,(k)]-A_{j}{ }^{i}{ }_{k}[j, k]-B_{j}{ }^{i}{ }_{k}[j,(k)], \\
& \Omega^{*(i)}=-\frac{1}{2} H^{* i}{ }_{j k}[j, k]-P^{* i}{ }_{j h} P^{h}{ }_{k}[j, k]-P^{* i}{ }_{j k}[j,(k)], \\
& {\left[\delta t_{0}^{i}\right]=\left[\delta P^{i}{ }_{k}, d x^{k}\right]+P^{i}{ }_{h}\left[\delta d x^{h}\right]} \\
& \quad=-P^{i}{ }_{j / k}[j, k]-P^{i}{ }_{j /(k)}[j,(k)]-P^{i}{ }_{h} C_{j}{ }^{h}{ }_{k}[j,(k)], \\
& {\left[t_{j}^{i} \delta y^{j}\right]=A_{k}{ }^{i}{ }_{j}[j,(k)], \quad\left(B_{j}{ }^{i}{ }_{k}=B_{k}{ }^{i}{ }_{j}\right),} \\
& {\left[t_{h}^{i} t_{0}^{h}\right]=-P^{h}{ }_{j} A_{h}{ }^{i}{ }_{k}[j, k]-P^{h}{ }_{j} B_{h}{ }^{i}{ }_{k}[j,(k)] .}
\end{aligned}
$$

Using the above and (2.2), we see from (2.11)

$$
\text { (a) } \begin{aligned}
H^{* i}{ }_{j k} & +\left(P^{* i}{ }_{j h} P^{h}{ }_{k}-j \mid k\right) \\
& =R^{i}{ }_{j k}+\left(P^{i}{ }_{j / k}+P^{h}{ }_{j} A_{h}{ }^{i}{ }_{k}-j \mid k\right), \\
\text { (b) } \quad P^{* i}{ }_{j k} & =P^{i}{ }_{j k}+P^{i}{ }_{j /(k)}-A_{k}{ }^{i}{ }_{j}+P^{i}{ }_{h} C_{j}{ }^{h}{ }_{k}+P^{h}{ }_{j} B_{h}{ }^{i}{ }_{k} \\
& =P^{i}{ }_{j k}+P^{i}{ }_{j(k)}-A_{k}{ }^{i}{ }_{j}+C_{h}{ }^{i}{ }_{k} P^{h}{ }_{j}+P^{h}{ }_{j} B_{h}{ }^{i}{ }_{k} \\
& =D_{j}{ }^{i}{ }_{k}-A_{k}{ }^{i}{ }_{j}+C^{*}{ }_{h}{ }_{k}{ }_{k} P^{h}{ }_{j} \\
& =D_{j}{ }^{i}{ }_{k}-A_{j}{ }^{i}{ }_{k}+C^{*}{ }_{h}{ }^{i}{ }_{j} P^{h}{ }_{k} .
\end{aligned}
$$

If we substitute $P^{* i}{ }_{j h}$ in $(2.12)(b)$ into $(a)$, then we have

$$
\begin{aligned}
H^{* i}{ }_{j k}-R^{i}{ }_{j k} & =P^{i}{ }_{j / k}+P^{h}{ }_{j} A_{h}{ }^{i}{ }_{k}-\left(D_{j}{ }^{i}{ }_{h}-A_{h}{ }^{i}{ }_{j}+C^{*}{ }_{r}{ }_{h}{ }_{h} P^{r}{ }_{j}\right) P^{h}{ }_{k}-j \mid k \\
& =P^{i}{ }_{j / k}+P^{h}{ }_{j} D_{h}{ }^{i}{ }_{k}-j \mid k=E^{i}{ }_{j k}, \quad((1.17)(b)) .
\end{aligned}
$$

Hence we have
Proposition 2.8. In a space $M_{n}$, the torsion tensors of $C F^{*}(G)$ and $C \Gamma(N)$ are related by the following equations:

$$
\begin{align*}
& \text { (a) } P^{* i}{ }_{j k}=D_{j}{ }^{i}{ }_{k}-A_{j}{ }^{i}{ }_{k}+C^{*}{ }_{j}{ }^{i}{ }_{r} P^{r}{ }_{k}, \\
&  \tag{2.13}\\
& { }^{*} \Gamma_{j}{ }^{i}{ }_{k}-F_{j}{ }^{i}{ }_{k}=D_{j}{ }^{i}{ }_{k}-P^{* i}{ }_{j k}=A_{j}{ }^{i}{ }_{k}-C^{*}{ }_{j}{ }^{i}{ }_{r} P^{r}{ }_{k}, \\
& \text { (b) } H^{* i}{ }_{j k}=R^{i}{ }_{j k}+E^{i}{ }_{j k}=H^{i}{ }_{j k} .
\end{align*}
$$

### 2.4. Curvature tensors of $\left[R^{*}\right]$ and $[R]$.

After the similar calculations of the metrical case, we have for the $h$-metrical case

Proposition 2.9. In a space $M_{n}$, the curvature tensors of $R F^{*}(G)$ and $R \Gamma(N)$ are related by the following equations:

$$
\text { (a) } \begin{align*}
& K^{*}{ }_{j}{ }_{k l}+{ }^{*} \Gamma_{j}{ }^{i}{ }_{k h} P^{h}{ }_{l}-{ }^{*} \Gamma_{j}{ }_{j}{ }_{l h} P^{h}{ }_{k} \\
&=K_{j}{ }^{i}{ }_{k l}+\left\{A_{j}{ }^{i}{ }_{k / l}-C^{*}{ }_{j}{ }^{i}{ }_{h / l} P^{h}{ }_{k}-C^{*}{ }_{j}{ }^{i}{ }_{h} P^{h}{ }_{k / l}\right.  \tag{2.14}\\
&\left.\quad+\left(A_{j}{ }^{h}{ }_{k}-C^{*}{ }_{j}{ }^{h}{ }_{r} P^{r}{ }_{k}\right)\left(A_{h}{ }^{i}{ }_{l}-C^{*}{ }_{h}{ }^{i}{ }_{r} P^{r}{ }_{l}\right)-k \mid l\right\},
\end{align*}
$$

$$
\text { (b) }{ }^{*} \Gamma_{j}{ }^{i}{ }_{k l}=F_{j}{ }^{i}{ }_{k l}+A_{j}{ }^{i}{ }_{k(l)}-C^{*}{ }_{j}{ }^{i}{ }_{h(l)} P^{h}{ }_{k}-C^{*}{ }_{j}{ }^{i}{ }_{h} P^{h}{ }_{k(l)} .
$$

2.5. The space $M_{n}$ with $C_{i j / k}=0$ or $C_{i j / 0}=0$.

Using Proposition 2.3 and Theorem 2.4, we have from (2.10), (2.12) and (2.14)

Proposition 2.10. In a space $M_{n}$ with $C_{i j / 0}=0$ we have
(a) $\quad P^{i}{ }_{k}=0, \quad A_{j}{ }^{i}{ }_{k}=\frac{1}{2} g^{* i h}\left(C_{h j / k}+C_{h k / j}-C_{j k / h}\right)$,
(b) $R^{*}{ }_{j}{ }^{i}{ }_{k l}=R_{j}{ }^{i}{ }_{k l}+B_{j}{ }^{i}{ }_{h} R^{h}{ }_{k l}+\left(A_{j}{ }^{i}{ }_{k / l}+A_{j}{ }^{h}{ }_{k} A_{h}{ }^{i}{ }_{l}-k \mid l\right)$,
(c) $K^{*}{ }_{j}{ }^{i}{ }_{k l}=K_{j}{ }^{i}{ }_{k l}+\left(A_{j}{ }^{i}{ }_{k / l}+A_{j}{ }^{h}{ }_{k} A_{h}{ }^{i}{ }_{l}-k \mid l\right)$,
(d) $\quad H^{i}{ }_{j k}=R^{i}{ }_{j k}, \quad P^{* i}{ }_{j k}=P^{i}{ }_{j k}-A_{j}{ }^{i}{ }_{k}, \quad E^{i}{ }_{j k}=0$,
(e) ${ }^{*} \Gamma_{j}{ }^{i}{ }_{k l}=F_{j}{ }^{i}{ }_{k l}+A_{j}{ }^{i}{ }_{k(l)}$.

Proposition 2.11. In a space $M_{n}$ with $C_{i j / k}=0$ we have
(a) $R^{*}{ }_{j}{ }^{i}{ }_{k l}=R_{j}{ }^{i}{ }_{k l}+B_{j}{ }^{i}{ }_{h} R^{h}{ }_{k l}$,
(b) $P^{*}{ }_{j}{ }^{i}{ }_{k l}=P_{j}{ }^{i}{ }_{k l}-B_{j}{ }^{i}{ }_{l / k}+B_{j}{ }^{i}{ }_{h} P^{h}{ }_{k l}, \quad P^{* i}{ }_{j k}=P^{i}{ }_{j k}$,
(c) $K^{*}{ }_{j}{ }^{i}{ }_{k l}=K_{j}{ }^{i}{ }_{k l}, \quad{ }^{*} \Gamma_{j}{ }^{i}{ }_{k l}=F_{j}{ }^{i}{ }_{k l}$.

## §3. A generalized metric space whose associated Finsler space is a Riemannian space

If the metric $g_{i j}$ is independent of $y: C_{j}{ }^{i}{ }_{k}=0$, then the space $M_{n}$ itself is a Riemannian space and then its associated Finsler space is also a Riemannian space from the definition.

Definition. A generalized metric space $M_{n}$ whose associated Finsler space $F_{n}^{*}(g)$ is a Riemannian space $\left(C^{*}{ }_{j}{ }^{i}{ }_{k}=0\right)$ is called an $R M_{n}$ space (abbreviation). If the Riemannian space is of constant curvature, then the space $M_{n}$ is called an $R c c M_{n}$ space.

By means of (2.1)(b) and Proposition 2.3, we see
Theorem 3.1. If an $R M_{n}$ space satisfies the condition $C_{i j /(k)}=0$, then the space is a Riemannian space.

From $(2.1)(b)$ and $(2.5)(b)$ we see

$$
\begin{equation*}
3 C^{*}{ }_{i j k}=C_{i j k}+C_{j k i}+C_{k i j}+\frac{1}{2}\left(C_{i j(k)}+C_{j k(i)}+C_{k i(j)}\right) \tag{3.1}
\end{equation*}
$$

Hence we have the following
Theorem 3.2. A space $M_{n}$ reduces to an $R M_{n}$ space if the following condition holds:

$$
C_{i j k}+C_{j k i}+C_{k i j}+\frac{1}{2}\left(C_{i j(k)}+C_{j k(i)}+C_{k i(j)}\right)=0
$$

S. Numata proved the following theorem ([8],Theorem 2): A Landsberg space (in the sense of Finsler geometry) of scalar curvature $K$ is a Riemannian space of constant curvature provided $K \neq 0$. Hence we have

Theorem 3.3. An $L M_{n}$ space (cf. §5) of scalar curvature $K$ is an $R c c M_{n}$ space.
C. Shibata proved the following theorem ([11], Theorem 4): If a Finsler space of scalar curvature satisfies the condition $P^{i}{ }_{h j / k}-j \mid k=0$ (in the notation of ordinary Finsler geometry), then the space is a Riemannian space of constant curvature. Hence we have

Theorem 3.4. If the Finsler space $F_{n}^{*}(g)$ of scalar curvature $K$ satisfies the condition $P^{* i}{ }_{h j}{ }^{*} k-j \mid k=0$, then the space is an $R c c M_{n}$ space.

From the theory of Finsler spaces, we see that in an $R M_{n}$ space we have the following relations:
(a) ${ }^{*} \Gamma_{j}{ }^{i}{ }_{k}=G^{*}{ }_{j}{ }^{i}{ }_{k}=G_{j}{ }^{i}{ }_{k}=\left\{{ }_{j}{ }^{i}{ }_{k}\right\}$,
(b) $\quad P^{* i}{ }_{j k}=0, \quad P^{*}{ }_{j}{ }^{i}{ }_{k l}={ }^{*} \Gamma_{j}{ }^{i}{ }_{k l}=G^{*}{ }_{j}{ }^{i}{ }_{k l}=G_{j}{ }^{i}{ }_{k l}=S^{*}{ }_{j}{ }^{i}{ }_{k l}=0$,
(c) $R^{*}{ }_{j}{ }^{i}{ }_{k l}=K^{*}{ }_{j}{ }^{i}{ }_{k l}=H^{*}{ }_{j}{ }^{i}{ }_{k l}=H_{j}{ }^{i}{ }_{k l}(x)$,
where $\left\{{ }_{j}{ }^{i} k\right.$ is the Christoffel symbol with respect to $g^{*}{ }_{i j}(x)$.
Using (2.10), (2.12), (2.13), (2.14) and (3.2), we have
Proposition 3.5. In an $R M_{n}$ space, we have

$$
\begin{align*}
& \text { (a) } \quad A_{j}{ }^{i}{ }_{k}=D_{j}{ }^{i}{ }_{k}=\frac{1}{2} g^{* i h}\left(C_{h j / k}+C_{h k / j}-C_{j k / h}\right), \\
& \\
& F_{j}{ }^{i}{ }_{k}=\left\{j_{j}{ }^{i}{ }_{k}\right\}-A_{j}{ }^{i}{ }_{k}, \quad C_{j}{ }^{i}{ }_{k}=-B_{j}{ }^{i}{ }_{k}, \\
& P^{i}{ }_{k l}=A_{k}{ }^{i}{ }_{l}-P^{i}{ }_{k(l)},  \tag{3.3}\\
& \text { (b) } \quad H_{j}{ }^{i}{ }_{k l}(x)=K_{j}{ }^{i}{ }_{k l}+E_{j}{ }^{i}{ }_{k l}, \quad H^{i}{ }_{j k}=R^{i}{ }_{j k}+E^{i}{ }_{j k}, \\
& \\
& E_{j}{ }^{i}{ }_{k l}=A_{j}{ }^{i}{ }_{k / l}+A_{j}{ }^{h}{ }_{k} A_{h}{ }^{i}{ }_{l}-k \mid l, \\
& \\
& E^{i}{ }_{j k}=P^{i}{ }_{j / k}+P^{h}{ }_{j} A_{h}{ }^{i}{ }_{k}-j \mid k, \\
& \text { (c) } \quad P_{j}{ }^{i}{ }_{k l}=-A_{j}{ }^{i}{ }_{k(l)}-C_{j}{ }^{i}{ }_{l / k}+C_{j}{ }^{i}{ }_{h} P^{h}{ }_{k l}, \\
& \\
& F_{j}{ }^{i}{ }_{k l}=-A_{j}{ }^{i}{ }_{k(l)}, \quad G_{j}{ }^{i}{ }_{k l}=0 .
\end{align*}
$$

Because of $g^{* i h}{ }_{(k)}=0$, Proposition 2.3 and $(3.2)(a)$, we can easily prove

Lemma 3.6. In an $R M_{n}$ space, the following four conditions are equivalent:
(a) $A_{j}{ }^{i}{ }_{k}=0$,
(b) $C_{h j / k}=0$,
(c) $A_{j}{ }^{i} k(l)=0$,
(d) $\quad C_{h j / k(l)}=0$.

Theorem 3.7. If an $R M_{n}$ space satisfies the condition $C_{h j / k}=0$, then the space $M_{n}$ is a $g$-Berwald space $\left(F_{j}{ }^{i} k l=0\right.$, cf. $\left.\S 5\right)$.

## §4. A generalized metric space whose associated Finsler space is a Minkowski space

Definition. If there exists a coordinate system such that the metric tensor $g_{i j}$ is independent of $x: g_{i j}(y)$ and $P^{i}{ }_{k}=0$, then the space $M_{n}$
is called a $g$-Minkowski space. If $C_{i j}=0$, then the $g$-Minkowski space is called a Minkowski space.

Definition. A generalized metric space $M_{n}$ whose associated Finsler space $F_{n}^{*}(g)$ is a Minkowski space is called an $M M_{n}$ space (abbreviation).

Remark. From the definition $g^{*}{ }_{i j}(y)=\dot{\partial}_{i} \dot{\partial}_{j}\left(g_{h k}(y) y^{h} y^{k}\right) / 2$, a $g$-Minkowski space is an $M M_{n}$ space. However, from the relation: $g^{*}{ }_{i j}(y)=$ $g_{i j}(x, y)+C_{i j}(x, y)$, being an $M M_{n}$ space $\left(\partial_{k} g^{*}{ }_{i j}=0\right)$ does not mean that the space $M_{n}$ is a $g$-Minkowski space $\left(\partial_{k} g_{i j}=0\right)$.

Theorem 4.1 (cf. [6],[12]). A necessary and sufficient condition for a generalized metric space $M_{n}$ to be a $g$-Minkowski space is that the curvature tensors $K_{j}{ }^{i}{ }_{k l}$ and $F_{j}{ }^{i}{ }_{k l}$ vanish $\left(\Omega_{j}^{i}=0\right.$ for $\left.R \Gamma(G)\right)$.

Proof. Let us assume that the generalized metric space $M_{n}$ is a $g$ Minkowski space. Then we have $F^{2}(x, y)=\bar{F}^{2}:=\bar{g}_{a b}(\bar{y}) \bar{y}^{a} \bar{y}^{b}$ in some suitable coordinate system, hence $\partial_{c} \bar{F}^{2}=\partial \bar{F}^{2} / \partial \bar{x}^{c}=0$. From the definition in $\S 1$, we find

$$
\begin{aligned}
& 4 \bar{G}^{a}=\bar{g}^{* a b}\left(\bar{y}^{c} \dot{\partial}_{b} \partial_{c} \bar{F}^{2}-\partial_{b} \bar{F}^{2}\right)=0, \quad \dot{\partial}_{b}=\partial / \partial \bar{y}^{b} \\
& \bar{N}_{b}^{a}=\bar{G}_{b}^{a}=0, \quad \partial_{c} \bar{g}_{a b}=0, \quad \bar{F}_{b}{ }^{a}{ }_{c}=0, \quad \bar{F}_{b}{ }^{a}{ }_{c d}=0, \quad \bar{K}_{b}{ }^{a}{ }_{c d}=0 .
\end{aligned}
$$

Conversely, $F_{j}{ }^{i}{ }_{k l}=F_{j}{ }^{i}{ }_{k(l)}=0$ means that the connection parameters $F_{j}{ }^{i}{ }_{k}$ are functions of $x^{i}$ only. Therefore the curvature tensor $K_{j}{ }^{i}{ }_{k l}$ is also a function of $x^{i}$ only. When $K_{j}{ }^{i}{ }_{k l}(x)=0$, we know as in a Riemannian space that there exists a coordinate system $\left(\bar{x}^{a}\right)$ for which the connection parameters $\bar{F}_{b}{ }^{a}{ }_{c}$ vanish, that is,

$$
\begin{equation*}
\bar{g}_{a d} \bar{F}_{b}{ }^{d}{ }_{c}=\frac{1}{2}\left(\partial_{b} \bar{g}_{a c}+\partial_{c} \bar{g}_{a b}-\partial_{a} \bar{g}_{b c}\right)=0, \quad \bar{N}_{c}^{a}=\bar{F}_{b}{ }^{a}{ }_{c} \bar{y}^{b}=0 . \tag{4.1}
\end{equation*}
$$

Making $+a \mid c$ in (4.1), we get $\partial_{a} \bar{g}_{b c}=0$ which means that $\bar{g}_{b c}$ does not contain $\bar{x}^{a}$. Moreover we get $\bar{P}^{a}{ }_{b}=0$ from (1.1).

Remark. From (1.7)(a), (b) and Theorem 5.14(cf. §5), we see that the conditions in Theorem 4.2 are equivalent to the conditions $R_{j}{ }^{i}{ }_{k l}=0$ and $C_{j}{ }^{i}{ }_{k / l}=0$ for $C \Gamma(N)$.

By virtue of a well known theorem on Finsler spaces, we have

Theorem 4.2. A necessary and sufficient condition for a generalized metric space $M_{n}$ to be an $M M_{n}$ space is that the curvature tensors $H_{j}{ }^{i}{ }_{k l}$ and $G_{j}{ }^{i}{ }_{k l}$ vanish $\left(\Omega_{j}^{i}=0\right.$ for $\left.B \Gamma(G)\right)$.

From the theory of Finsler spaces, in an $M M_{n}$ space, we have

$$
\begin{align*}
& \text { (a) } R^{*}{ }_{j}{ }^{i}{ }_{k l}=K^{*}{ }_{j}{ }^{i}{ }_{k l}=H^{*}{ }_{j}{ }^{i}{ }_{k l}=H_{j}{ }^{i}{ }_{k l}=0, \\
& R^{* i}{ }_{j k}=H^{* i}{ }_{j k}=H^{i}{ }_{j k}=0, \\
& \text { (b) } C^{*}{ }_{j}{ }^{i}{ }_{k}{ }^{*}{ }_{l l}={ }^{*} \Gamma_{j}{ }^{i}{ }_{k l}=G^{*}{ }_{j}{ }^{k}{ }_{k l}=G_{j}{ }^{i}{ }_{k l}=0,  \tag{4.2}\\
& \\
& P^{* i}{ }_{j k}=0, \quad P^{*}{ }_{h}{ }^{i}{ }_{j k}=0 .
\end{align*}
$$

Using the relations in $\S 2$ and (4.2), we obtain
Proposition 4.3. In an $M M_{n}$ space, we have
(a) $D_{j}{ }^{i}{ }_{k}=A_{j}{ }^{i}{ }_{k}-C^{*}{ }_{j}{ }^{i}{ }_{h} P^{h}{ }_{k}, \quad R^{i}{ }_{j k}=-E^{i}{ }_{j k}$,
(b) $R_{j}{ }^{i}{ }_{k l}-S^{*}{ }_{j}{ }^{i}{ }_{r s} P^{r}{ }_{k} P^{s}{ }_{l}-B_{j}{ }^{i}{ }_{h} E^{h}{ }_{k l}=-A_{j}{ }^{i}{ }_{k / l}-A_{j}{ }^{h}{ }_{k} A_{h}{ }^{i}{ }_{l}-k \mid l$,
(c) $F_{j}{ }^{i}{ }_{k l}=-A_{j}{ }^{i}{ }_{k(l)}+C^{*}{ }_{j}{ }^{i}{ }_{h(l)} P^{h}{ }_{k}+C^{*}{ }_{j}{ }^{i}{ }_{h} P^{h}{ }_{k(l)}$,
(d) $\quad P_{j}{ }^{i}{ }_{k l}=S^{*}{ }_{j}{ }^{i}{ }_{h l} P^{h}{ }_{k}-A_{j}{ }^{i}{ }_{k /(l)}+B_{j}{ }^{i}{ }_{l / k}-A_{j}{ }^{i}{ }_{h} C_{k}{ }^{h}{ }_{l}-B_{j}{ }^{i}{ }_{h} P^{h}{ }_{k l}$

$$
-A_{j}{ }^{h}{ }_{k} B_{h}{ }^{i}{ }_{l}+B_{j}{ }^{h}{ }_{l} A_{h}{ }^{i}{ }_{k} .
$$

In virtue of Proposition 2.3 and $C_{j k / 0}=2 g^{*}{ }_{j h} P^{h}{ }_{k}$, we have that if an $M M_{n}$ space satisfies the condition $C_{i j / k}=0$, then the following relations hold:

$$
\begin{aligned}
& \text { (a) } D_{j}{ }^{i}{ }_{k}=0, \quad(b) \quad R_{j k}^{i}=-E^{i}{ }_{j k}=0, \quad P_{j k}^{i}=0, \\
& \text { (c) } R_{j}{ }^{i}{ }_{k l}=K_{j}{ }^{i}{ }_{k l}=0, \quad \text { (d) } \quad F_{j}{ }^{i}{ }_{k l}=C_{j}{ }^{i}{ }_{k / l}=0 .
\end{aligned}
$$

Hence we have
Theorem 4.4. If an $M M_{n}$ space satisfies the condition $C_{i j / k}=0$, then the space is a $g$-Minkowski space.

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