Publ. Math. Debrecen 54 / 3-4 (1999), 451–456

On a class of QR-submanifolds of quaternion space forms

By CALIN AGUT (Oradea)

Abstract. Let M be a QR-submanifolds (cf. A. BEJANCU [2]) of a quaternion space form N(c) such that every geodesic of M is a circle of N(c). Then we prove that either c = 0 or M is a totally real submanifold.

1. Introduction

Let N be a quaternion Kaehlerian manifold of real dimension 4n. Then there exist on N a Riemannian metric g and a vector bundle V of tensors of type (1,1) with a local basis of Hermitian structures J_1 , J_2 , J_3 such that $J_1J_2 = -J_2J_1 = J_3$. Moreover, for each local section S of V and vector field X on N, $\tilde{\nabla}_X S$ is also a section of V, where $\tilde{\nabla}$ is the Levi–Civita connection on N with respect to g. If the quaternion sectional curvature of N is a constant c then we say that N is a quaternion space form and denote it by N(c). As it is well known (cf. K. YANO and M. KON [10], p. 172) the curvature tensor \tilde{R} of $\tilde{\nabla}$ on N(c) is given by

(1.1)
$$\widetilde{R}(X,Y)Z = \frac{c}{4} \Big\{ g(Y,Z)X - g(X,Z)Y + \sum_{a=1}^{3} \{ g(J_aY,Z)J_aX - g(J_aX,Z)J_aY + 2g(X,J_aY)J_aZ \} \Big\}$$

for any $X, Y, Z \in \Gamma(TN(c))$.

Mathematics Subject Classification: 53C25, 53C40.

Key words and phrases: QR-submanifolds, quaternionic space forms, second fundamental forms. Calin Agut

Throughout the paper we use the following notations:

F(N) – the algebra of smooth functions on N,

 $\Gamma(E)$ – the F(N)-module of smooth sections of a vector bundle E over N. The same notations will be used for any other manifold.

Next, we consider an *m*-dimensional Riemannian manifold M isometrically immersed in N. Then M is said to be a *quaternion-real submanifold* (*QR-submanifold*) (cf. A. BEJANCU [2]) if there exist a vector subbundle ν of the normal bundle TM^{\perp} such that

$$J_a(\nu_x) = \nu_x$$
 and $J_a(\nu_x^{\perp}) \subset T_x M$

for any $x \in M$ and $a \in \{1, 2, 3\}$, where ν^{\perp} is the complementary orthogonal vector bundle to ν in TM^{\perp} . If, in particular, $\nu = TM^{\perp}$ (resp. $\nu = \{0\}$), M is said to be a quaternion submanifold (cf. B.Y. CHEN [4]) (resp. anti-quaternion submanifold, cf. J.S. PAK [8]).

Denote by s the rank of ν^{\perp} , that is, each fibre of ν^{\perp} is of dimension s. Then consider the s-dimensional vector subspaces $D_{a,x} = J_a(\nu_x^{\perp})$, $a \in \{1,2,3\}$ of $T_x M$ which are mutually orthogonal. Thus we obtain a globally defined distribution

$$D^{\perp}: x \to D_x^{\perp} = D_{1,x} \oplus D_{2,x} \oplus D_{3,x},$$

on M. Also, we have

$$J_a(D_{a,x}) = \nu_x^{\perp}$$
 and $J_a(D_{b,x}) = D_{c,x}$

for any $x \in M$, where (a, b, c) is a cyclic permutation of (1, 2, 3). Denote by D the complementary orthogonal distribution to D^{\perp} in TM. It is easy to see that D is a quaternion distribution on M, that is, $J_a(D_x) = D_x$ for any $x \in M$ and $a \in \{1, 2, 3\}$.

Finally, we recall from K. NOMIZU and K. YANO [6] the notion of circle in N. A curve C: x = x(t) with arc-length parameter t in N is said to be a *circle* if there exists a field of unit vectors Y_t along C, which, together with the unit tangent vectors X_t , satisfies the differential equations

(1.2)
$$\widetilde{\nabla}_t X_t = k Y_t \text{ and } \widetilde{\nabla}_t Y_t = -k X_t,$$

where k is a positive constant.

The main purpose of this note is to prove the following

Theorem 1. Let M be a QR-submanifold of N(c), such that each geodesic of M is a circle in N(c). Then either c = 0 or $D = \{0\}$.

452

On a class of QR-submanifolds of quaternion space forms

2. Preliminaries

First, from the general theory of submanifolds we recall the formulas of Gauss and Weingarten (cf. B.Y. CHEN [3], p. 39):

(2.1)
$$\widetilde{\nabla}_X Y = \nabla_X Y + h(X,Y), \quad \forall X,Y \in \Gamma(TM)$$

and

(2.2)
$$\widetilde{\nabla}_X \xi = -A_{\xi} X + \nabla_X^{\perp} \xi, \quad \forall X \in \Gamma(TM), \ \xi \in \Gamma(TM^{\perp}),$$

respectively, where ∇ , ∇^{\perp} , h and A_{ξ} are the Levi–Civita connection on M, the normal connection of M, the second fundamental form and the shape operator of M, respectively. Also, h and A_{ξ} are related by

(2.3)
$$g(h(X,Y),\xi) = g(A_{\xi}X,Y), \quad \forall X,Y \in \Gamma(TM), \ \xi \in \Gamma(TM^{\perp}).$$

The covariant derivative of h is defined by

(2.4)
$$(\nabla_X h)(Y,Z) = \nabla_X^{\perp}(h(Y,Z)) - h(\nabla_X Y,Z) - h(Y,\nabla_X Z),$$
$$\forall X, Y, Z \in \Gamma(TM).$$

Then the Codazzi equation is given by

(2.5)
$$\widetilde{R}(X,Y)Z\}^{\perp} = (\nabla_X h)(Y,Z) - (\nabla_Y h)(X,Z), \quad \forall X, Y, Z \in \Gamma(TM),$$

where $\{*\}^{\perp}$ means the normal part of *.

Now, suppose M is a QR-submanifold of a quaternion Kaehlerian manifold N. Then according to C.L. BEJAN [1] the second fundamental form of M satisfies

(2.6)
$$g(h(X,Y),\xi) = 0, \quad \forall X, Y \in \Gamma(D), \ \xi \in \Gamma(v).$$

Let C : x = x(t) be a geodesic of M, that is, $\nabla_t X_t = 0$. Thus from (2.1) we deduce

$$\nabla_t X_t = h(X_t, X_t),$$

which, together with (2.2), implies

(2.7)
$$\widetilde{\nabla}_t^2 X_t = -A_{h(X_t, X_t)} X_t + \nabla_t^{\perp}(h(X_t, X_t)).$$

Suppose now C is a circle in N. Then by using (2.1) and (1.2) we deduce

(2.8)
$$\widetilde{\nabla}_t^2 X_t = -k^2 X_t.$$

Comparing (2.7) and (2.8) we infer

(2.9)
$$A_{h(X_t, X_t)}X_t = k^2 X_t,$$

and

(2.10)
$$\nabla_t^{\perp}(h(X_t, X_t) = 0.$$

Consider t = 0. Using (2.3) and (2.9) we obtain

$$g(h(X,X),h(X,X)) = k^2$$

for any unit tangent vector X at a point $x \in M$. Thus there exists a non-zero function λ such that

(2.11)
$$g(h(X,X),h(X,X)) = \lambda^2,$$

for any unit vector field X on M. According to O'NEILL [7], the immersion of M in N(c) is λ -isotropic. From (2.11) we deduce

(2.12)
$$g(h(X,X),h(X,X)) = \lambda^2 g(X,X)g(X,X), \quad \forall X \in \Gamma(TM),$$

which is equivalent to

(2.13)
$$g(h(X,Y),h(Z,U)) + g(X,Z),h(U,Y)) + g(X,U),h(Y,Z)) = \lambda^2 \{g(X,Y)g(Z,U) + g(X,Z)g(U,Y) + g(X,U)g(Y,Z)\},\$$

for any $X, Y, Z, U \in \Gamma(TM)$. Also, from (2.10) and (2.4), taking into account that C is a geodesic, we deduce:

(2.14)
$$(\nabla_X h)(X, X) = 0, \quad \forall X \in \Gamma(TM),$$

which is equivalent to

(2.15)
$$(\nabla_X h)(Y,Z) + (\nabla_Y h)(X,Z) + (\nabla_Z h)(X,Y) = 0,$$
$$\forall X, Y, Z \in \Gamma(TM).$$

454

Remark 1. K. NOMIZU [5] obtained both (2.11) and (2.14) for a Kaehler submanifold of a complex projective space. Actually, it is easy to see that the above calculations hold good for a Riemannian submanifold whose geodesics are circles in the ambient space.

3. Proof of the Theorem

First, differentiating (2.11) and taking account of (2.14) we deduce $X(\lambda) = 0$ for any $X \in \Gamma(TM)$ that is, λ is locally constant on M. Then we take $Y = Z \in \Gamma(D)$ and $X \in \Gamma(D)$ in (2.15) and obtain

$$(\nabla_X h)(Y, Y) + 2(\nabla_Y h)(X, Y) = 0.$$

On the other hand, by using (1.1) in (2.5) we derive

$$(\nabla_X h)(Y,Y) - (\nabla_Y h)(X,Y) = 0, \quad \forall X,Y \in \Gamma(D).$$

Hence we have

(3.1)
$$(\nabla_X h)(Y,Y) = 0, \quad \forall X, Y \in \Gamma(D)$$

Next, we take $Y = Z = U \in \Gamma(D)$, $X = J_1 \eta$ for $\eta \in \Gamma(\nu^{\perp})$ in (2.13) and differentiate (2.13) with respect to $W \in \Gamma(D)$. Then taking into account that λ is locally constant and by using (3.1) we obtain

(3.2)
$$g((\nabla_W h)(J_1\eta, Y), h(Y, Y)) = 0, \quad \forall Y, W \in \Gamma(D), \ \eta \in \Gamma(\nu^{\perp}).$$

By using again (1.1) and (2.5) we deduce

$$(\nabla_W h)(J_1\eta, Y) - (\nabla_{J_1\eta} h)(W, Y) = \frac{c}{4}g(J_1W, Y)\eta,$$

and

$$(\nabla_W h)(J_1\eta, Y) - (\nabla_Y h)(W, J_1\eta) = \frac{c}{2}g(J_1W, Y)\eta.$$

Adding the last two relations and taking account of (2.15) we get

$$(\nabla_W h)(J_1\eta, Y) = \frac{c}{4}g(J_1W, Y)\eta,$$

which together with (3.2) implies

(3.3)
$$\frac{c}{4}g(J_1W,Y)g(\eta,h(Y,Y)) = 0, \quad \forall Y, W \in \Gamma(D), \ \eta \in \Gamma(\nu^{\perp}).$$

456 Calin Agut : On a class of QR-submanifolds of quaternion space forms

Finally, we suppose $c \neq 0$ and $D \neq \{0\}$. Then we take $Y = J_1 W$ in (3.3) and by linearity obtain:

(3.4)
$$g(h(X,Y),\eta) = 0, \quad \forall X, Y \in \Gamma(D), \ \eta \in \Gamma(\nu^{\perp}).$$

As a consequence of (2.6) and (3.4) we deduce h(X, Y) = 0 for any $X, Y \in \Gamma(D)$, which contradict (2.11). This completes the proof of the theorem.

References

- C.-L. BEJAN, On QR-submanifolds of a quaternion Kaehlerian manifold, Tensor 46 (1987), 413–417.
- [2] A. BEJANCU, Geometry of CR-submanifolds, D. Reidel Publish. Comp., Dordrecht, 1986.
- [3] B.-Y. CHEN, Geometry of submanifolds, M. Dekker, New York, 1973.
- B.-Y. CHEN, Totally umbilical submanifolds of quaternion space forms, J. Austral. Math. Soc. 26 (1978), 154–162.
- [5] K. NOMIZU, A characterization of the Veronese varieties, Nagoya Math. J. 60 (1976), 181–188.
- [6] K. NOMIZU and K. YANO, On circles and spheres in Riemannian geometry, Math. Ann. 21 (1974), 163–170.
- [7] B. O'NEILL, Isotropic and Kaehler immersions, Canad. J. Math. 17 (1965), 905–915.
- [8] J. S. PAK, Anti-quaternion submanifolds of quaternion projective space, Kyungpook Math. J. 18 (1981), 91–115.
- [9] K. TSUKADA, Parallel submanifolds in a quaternion projective space, Osaka J. Math. 22 (1985), 187–241.
- [10] K. YANO and M. KON, Structures on manifolds, World Scientific, Singapore, 1984.

CALIN AGUT DEPARTMENT OF MATHEMATICS UNIVERSITY OF ORADEA STR. ARMATEI ROMANE NR. 5 ORADEA – 3700 ROMANIA

(Received December 1, 1997; revised July 7, 1998)