# Some new geometric structures on the tangent bundle 

By V. OPROIU (Iaşi)


#### Abstract

One obtains a Kähler Einstein structure on the tangent bundle of a Riemannian manifold of constant negative sectional curvature. If the constant sectional curvature is positive then a Kähler Einstein structure is defined in a tube around zero section in the tangent bundle. Moreover, the holomorphic sectional curvature of the obtained Kähler Einstein structure is constant. Two special cases are also studied.


## Introduction

It is well known that the tangent bundle $T M$ of a Riemannian manifold $(M, g)$ can be organized as an almost Kählerian manifold (see [3], [10], [9]) by using the splitting of the tangent bundle to $T M$ into the vertical and horizontal distributions VTM, HTM (the last one being defined by the Levi Civita connection on $M$ ), the Sasaki metric and an almost complex structure defined by the above splitting (see also [18], [19], [6]). However, this structure is Kähler only in the case where the base manifold is locally Euclidean. The Sasaki metric is not a "good" metric in the sense of [1] since its Ricci curvature is not constant, i.e. the Sasaki metric is not, generally, Einstein.

In this paper we shall present some interesting Kähler structures defined on the tangent bundle of a Riemannian manifold $(M, g)$ of constant sectional curvature obtained by adapting an idea of Calabi ([2], [1]) to

[^0]define a hyperKähler structure on the cotangent bundle of a Kähler manifold having constant positive holomorphic sectional curvature (the complex projective space). The found structures are defined by functions on $T M$, depending explicitely on the energy density (kinetic energy) on $T M$, only. In some cases, the obtained Kähler structures on $T M$ have some supplimentary properties: are locally symmetric, have constant holomorphic sectional curvature etc.

In [13] we have been interested in finding a Kähler Einstein structure on the tangent bundle of a space form. We have considered a Riemannian metric $G$ defined on the tangent bundle by using an $M$-tensor field on $T M$ obtained in the following way. Denote by $\tau: T M \rightarrow M$ the canonical projection of the tangent bundle on the base manifold. Let $y$ be the current tangent vector of $T M$, denote by

$$
t=\frac{1}{2}\|y\|^{2}=\frac{1}{2} g_{\tau(y)}(y, y)
$$

the energy density in $y$ and let $g_{y} \in T^{*} M$ be the cotangent vector obtained from $y$ by the "musical" isomorphism between $T M$ and $T^{*} M$ defined by $g$ (the "lowering" of indices). Then we may consider the following symmetric $M$-tensor field of type ( 0,2 ) on $T M$

$$
\widetilde{G}=u(t) g+v(t) g_{y} \otimes g_{y},
$$

where $g$ is thought of as an $M$-tensor field on $T M([7])$ and $u, v:[0, \infty) \rightarrow \mathbb{R}$ are smooth real valued functions depending on $t$ only. We assume that the values of $u$ and $u+2 t v$ are positive, assuring that $\widetilde{G}$ is positive definite. Later on, we shall study the condititions under which these properties of $u, v$ are fulfilled. If we try to find the expressions of the functions $u, v$ in order to obtain an Einstein metric on $T M$ defined by using the $M$ tensor field $\widetilde{G}$, it is convenient to use an almost complex structure $J$ on $T M$, related to the considered metric, such that we shall obtain, in fact, a Kähler Einstein structure on $T M$ in the case where $(M, g)$ has constant (negative) sectional curvature. As a matter of fact, we shall obtain the existence of a Kähler Einstein structure even in the case where ( $M, g$ ) has positive constant sectional curvature, but only in a tube around the zero section in $T M$ (Theorem 4). The surprising fact was that we have obtained on $T M$ a structure of Kähler manifold with constant holomorphic sectional curvature (Theorem 5).

However, during the computations, we had to exclude two important cases which appeared, in a certain sense, as singular cases. One of them is the case where the metric is obtained from a Lagrangian depending on the density energy (in this case $v$ is the derivative of $u$ ). The second special case is the case where $u=$ constant. We have studied, separately, the case where $u=1$, obtaining $v=-c$, where $c$ is the constant sectional curvature of the Riemannian manifold $(M, g)$. In this case the found Kähler Einstein structure is locally symmetric.

There is also another singular case when $u=A t, A \in \mathbb{R}_{+}^{*}$. In this case we obtain a Kähler Einstein structure on a tube around zero section in the tangent bundle of a Riemannian manifold of positive constant sectional curvature.

The manifolds, tensor fields and geometric objects we consider in this paper, are assumed to be differentiable of class $C^{\infty}$ (i.e. smooth). We use the computations in local coordinates in a fixed local chart, but many results from this paper may be expressed in an invariant form. The well known summation convention is used throughout this paper, the range for the indices $i, j, k, l, h, s, r$ being always $\{1, \ldots, n\}$ (see [5], [4], [14], [15]). We shall denote by $\Gamma(T M)$ the module of smooth vector fields on $T M$.

Acknowledgements. Some components of the curvature tensor field of the considered Riemannian metric have quite complicate expressions. We have used the Mathematica package RICCI for doing tensor calculations, elaborated by J.M. LEE in order to work with such complicate expressions. Thus, some of these expressions are not written down in this paper but it is indicated how they can be obtained by using RICCI. The author is grateful to Eng. Victor Fecioru from Brisbane, Australia, for helping him with some advices, software and hardware, necessary in the computations made by using RICCI.

## 1. An almost Kähler structure on the tangent bundle

Let $(M, g)$ be a smooth $n$-dimensional Riemannian manifold and denote its tangent bundle by $\tau: T M \longrightarrow M$. Recall that $T M$ has a structure of $2 n$-dimensional smooth manifold induced from the smooth manifold structure of $M$. A local chart $(U, \varphi)=\left(U, x^{1}, \ldots, x^{n}\right)$ on $M$ induces a local chart $\left(\tau^{-1}(U), \Phi\right)=\left(\tau^{-1}(U), x^{1}, \ldots, x^{n}, y^{1}, \ldots, y^{n}\right)$ on $T M$ where the local coordinates $x^{i}, y^{i} ; i=1, \ldots, n$ are defined as follows. The first $n$
local coordinates $x^{i}=x^{i} \circ \tau ; i=1, \ldots, n$ on $T M$ are the local coordinates in the local chart $(U, \varphi)$ of the base point of a tangent vector from $\tau^{-1}(U)$. The last $n$ local coordinates $y^{i} ; i=1, \ldots, n$ are the vector space coordinates of the same tangent vector, with respect to the natural local basis in the corresponding tangent space, defined by the local chart $(U, \varphi)$.

This special structure of $T M$ allows us to introduce the notion of $M$-tensor field on it (see [7]). An $M$-tensor field of type ( $p, q$ ) on $T M$ is defined by sets of functions

$$
T_{j_{1} \ldots j_{q}}^{i_{1} \ldots i_{p}}(x, y) ; \quad i_{1}, \ldots, i_{p}, j_{1}, \ldots, j_{q}=1, \ldots, n,
$$

assigned to any induced local chart $\left(\tau^{-1}(U), \Phi\right)$ on $T M$, such that the change rule is that of the components of a tensor field of type $(p, q)$ on the base manifold, when a change of local charts on the base manifold is performed. The components $y^{i}$ of the tangent vector $y$ define an $M$ tensor field of type $(1,0)$. Every usual tensor field on the base manifold may be thought of as an $M$-tensor field on $T M$, having the same type, with the components in the induced local chart on $T M$, equal to the local coordinate components of the given tensor field in the chosen local chart on the base manifold. The $M$-tensor field on the tangent bundle associated to a covariant tensor field on the base manifold $M$ may be thought of as the pull back of the given tensor field by the smooth submersion $\tau: T M \longrightarrow M$. E.g. the components $g_{i j}$ of the metric tensor field $g$ define an $M$-tensor field of type $(0,2)$ on $T M$. The components $g_{0 i}=g_{k i} y^{k}$ define an $M$-tensor field of type $(0,1)$ on $T M$.

The tangent bundle $T M$ of a Riemannian manifold $(M, g)$ can be organized as a Riemannian or a pseudo-Riemannian manifold in many ways. The most known such structures are given by the Sasaki metric on $T M$ defined by $g$ (see [18], [3]) and the complete lift type pseudoRiemannian metric defined by $g$ (see [19], [20], [10], [11]). Recall that the Levi Civita connection of $g$ defines a direct sum decomposition

$$
\begin{equation*}
T T M=V T M \oplus H T M, \tag{1}
\end{equation*}
$$

of the tangent bundle to $T M$ into the vertical distribution $V T M=\operatorname{Ker} \tau_{*}$ and the horizontal distribution $H T M$ defined by the Levi Civita connection $\dot{\nabla}$ of $g$. The vector fields $\left(\frac{\partial}{\partial y^{1}}, \ldots, \frac{\partial}{\partial y^{n}}\right)$ define a local frame field for $V T M$ and for $H T M$ we have the local frame field $\left(\frac{\delta}{\delta x^{1}}, \ldots, \frac{\delta}{\delta x^{n}}\right)$, where

$$
\frac{\delta}{\delta x^{i}}=\frac{\partial}{\partial x^{i}}-\Gamma_{i 0}^{h} \frac{\partial}{\partial y^{h}}, \quad \Gamma_{i 0}^{h}=\Gamma_{i k}^{h} y^{k}
$$

and $\Gamma_{i k}^{h}(x)$ are the Christoffel symbols defined by the Riemannian metric $g$.
The distributions VTM and HTM are isomorphic to each other and it is possible to derive an almost complex structure on $T M$ which, together with the Sasaki metric, determines a structure of almost Kählerian manifold on $T M$ (see [3]). Consider now the energy density (kinetic energy or "forza viva", according to the terminology used by Levi Civita)

$$
\begin{equation*}
t=\frac{1}{2} g_{i k}(x) y^{i} y^{k}=\frac{1}{2}\|y\|^{2}=\frac{1}{2} g_{\tau(y)}(y, y), \tag{2}
\end{equation*}
$$

defined on $T M$ by the Riemannian metric $g$ of $M$, where $g_{i k}$ are the components of $g$ in the local chart $(U, \varphi)$. Let $u, v:[0, \infty) \rightarrow \mathbb{R}$ be two real smooth functions. We shall assume that $u, u+2 t v$ have positive values. Then we may consider the following symmetric $M$-tensor field of type $(0,2)$ on $T M$, defined by the components (see [16], [12])

$$
\begin{equation*}
G_{i j}=u(t) g_{i j}+v(t) g_{0 i} g_{0 j}, \tag{3}
\end{equation*}
$$

where $g_{0 i}=g_{h i} y^{h}$. The matrix $\left(G_{i j}\right)$ is symmetric. Studying the property of the quadratic form $G_{i j} z^{i} z^{j}$ to be positive for all nonzero vectors $\left(z^{1}, \ldots, z^{n}\right)$, we obtain the conditions $u>0, u+2 t v>0$. The inverse of the matrix (Gij) has the entries

$$
\begin{equation*}
H^{k l}=\frac{1}{u} g^{k l}+w y^{k} y^{l}, \tag{4}
\end{equation*}
$$

where $g^{k l}$ are the components of the inverse of the matrix $\left(g_{i j}\right)$ and

$$
\begin{equation*}
w=w(t)=-\frac{v}{u(u+2 t v)} . \tag{5}
\end{equation*}
$$

The components $H^{k l}(x, y)$ are well defined and define a symmetric $M$ tensor field of type $(2,0)$ on $T M$. We shall use also the components $H_{i j}(x, y)$ of a symmetric $M$-tensor field of type $(0,2)$ obtained from the components $H^{k l}$ by "lowering" the indices

$$
\begin{equation*}
H_{i j}=g_{i k} H^{k l} g_{l j}=\frac{1}{u} g_{i j}+w g_{0 i} g_{0 j} . \tag{6}
\end{equation*}
$$

Throughout this paper we shall use also the following $M$-tensor fields on $T M$

$$
\left\{\begin{align*}
G^{k l} & =g^{k i} G_{i j} g^{j l}=u g^{k l}+v y^{k} y^{l}, G_{k}^{i}=G^{i h} g_{h k}=G_{k h} g^{h i}  \tag{7}\\
& =u \delta_{k}^{i}+v y^{i} g_{0 k}, H_{k}^{i}=H^{i h} g_{h k}=H_{k h} g^{h i}=\frac{1}{u} \delta_{k}^{i}+w y^{i} g_{0 k} .
\end{align*}\right.
$$

Remark that the matrix $\left(H_{k}^{i}\right)$ is the inverse of the matrix $\left(G_{k}^{i}\right)$. The following Riemannian metric may be considered on $T M$

$$
\begin{equation*}
G=G_{i j} d x^{i} d x^{j}+H_{i j} \dot{\nabla} y^{i} \dot{\nabla} y^{j}, \tag{8}
\end{equation*}
$$

where $\dot{\nabla} y^{i}=d y^{i}+\Gamma_{j 0}^{i} d x^{j}$ is the absolute differential of $y^{i}$ with respect to the Levi Civita connection $\dot{\nabla}$ of $g$. Equivalently, we have

$$
\begin{aligned}
& G\left(\frac{\delta}{\delta x^{i}}, \frac{\delta}{\delta x^{j}}\right)=G_{i j} \\
& G\left(\frac{\partial}{\partial y^{i}}, \frac{\partial}{\partial y^{j}}\right)=H_{i j} \\
& G\left(\frac{\partial}{\partial y^{i}}, \frac{\delta}{\delta x^{j}}\right)=G\left(\frac{\delta}{\delta x^{j}}, \frac{\partial}{\partial y^{i}}\right)=0 .
\end{aligned}
$$

Remark that HTM, VTM are orthogonal to each other with respect to $G$ but the Riemannian metrics induced from $G$ on $H T M, V T M$ are not isometric, so the considered metric $G$ on $T M$ is no longer a metric of Sasaki type. Remark also that the system of 1-forms $\left(d x^{1}, \ldots, d x^{n}, \dot{\nabla} y^{1}, \ldots, \dot{\nabla} y^{n}\right)$ defines a local frame of $T^{*} T M$, dual to the local frame $\left(\frac{\delta}{\delta x^{1}}, \ldots, \frac{\delta}{\delta x^{n}}, \frac{\partial}{\partial y^{1}}\right.$, $\left.\ldots, \frac{\partial}{\partial y^{n}}\right)$ adapted to the direct sum decomposition (1).

An almost complex structure $J$ may be defined on $T M$ by

$$
\begin{equation*}
J \frac{\delta}{\delta x^{i}}=G_{i}^{k} \frac{\partial}{\partial y^{k}} ; \quad J \frac{\partial}{\partial y^{i}}=-H_{i}^{k} \frac{\delta}{\delta x^{k}} . \tag{9}
\end{equation*}
$$

Then we obtain obtain by a straightforward computation
Theorem 1. $(T M, G, J)$ is an almost Kählerian manifold.
The associated 2 -form $\Omega$ is given by

$$
\begin{equation*}
\Omega=g_{i j} \dot{\nabla} y^{i} \wedge d x^{j} \tag{10}
\end{equation*}
$$

and it is closed since it does coincide with the 2-form associated to the Sasaki metric on TM (see [3]).

## 2. A Kähler structure on $T M$

In this section we shall study the integrability of the almost complex structure defined by $J$ on $T M$. To do this we need the following well known formulas for the brackets of the vector fields $\frac{\partial}{\partial y^{i}}, \frac{\delta}{\delta x^{i}} ; i=1, \ldots, n$

$$
\begin{align*}
& {\left[\frac{\partial}{\partial y^{i}}, \frac{\partial}{\partial y^{j}}\right]=0 ; \quad\left[\frac{\partial}{\partial y^{i}}, \frac{\delta}{\delta x^{j}}\right]=-\Gamma_{i j}^{h} \frac{\partial}{\partial y^{h}} ;}  \tag{11}\\
& {\left[\frac{\delta}{\delta x^{i}}, \frac{\delta}{\delta x^{j}}\right]=-R_{0 i j}^{h} \frac{\partial}{\partial y^{h}},}
\end{align*}
$$

where $R_{0 i j}^{h}=R_{k i j}^{h} y^{k}$ and $R_{k i j}^{h}$ are the local coordinate components of the curvature tensor field of $\dot{\nabla}$ on $M$.

Theorem 2. The almost complex structure $J$ on $T M$ is integrable if $(M, g)$ has constant sectional curvature $c$ and the function $v$ is given by

$$
\begin{equation*}
v=\frac{c-u u^{\prime}}{2 t u^{\prime}-u} . \tag{12}
\end{equation*}
$$

Of course we have to study the conditions under which $u+2 t v$ has positive values. From the conditon

$$
N_{J}=0
$$

it follows that the curvature tensor field of $\dot{\nabla}$ must have the expression

$$
\begin{equation*}
R_{h i j}^{k}=c\left(\delta_{i}^{k} g_{h j}-\delta_{j}^{k} g_{h i}\right), \tag{13}
\end{equation*}
$$

where $c$ is a constant and then we obtain the expression (12) of $v$. Next, we obtain easily the expression of the function $w$

$$
\begin{equation*}
w=w(t)=\frac{u u^{\prime}-c}{u\left(2 t c-u^{2}\right)} . \tag{14}
\end{equation*}
$$

## 3. A Kähler Einstein structure on $T M$

In this section we shall study the property of $(T M, G)$ to be Einstein. We shall find the expression of the Levi Civita connection $\nabla$ of the metric $G$ on $T M$, then we shall find the expression of the curvature tensor field of $\nabla$.

Then, computing the corresponding traces we shall find the components of the Ricci tensor field of $\nabla$. Asking for the Ricci tensor field to be proportional with the metric $G$ we find a second order ordinary differential equation which must be fulfilled by the function $u$. Fortunately, we have been able to find the general solution of this differential equation. For a special value of one of the integration constants we obtained the property of $G$ to be Einstein. At the same time we have been able to study the conditions under which the functions $u, u+2 t v$ have positive values.

Recall that the Levi Civita connection $\nabla$ on a Riemannian manifold $(M, g)$ is obtained from the formula

$$
\begin{gathered}
2 g\left(\nabla_{X} Y, Z\right)=X(g(Y, Z))+Y(g(X, Z))-Z(g(X, Y)) \\
+g([X, Y], Z)-g([X, Z], Y)-g([Y, Z], X) ; \quad \forall X, Y, Z \in \chi(M)
\end{gathered}
$$

and is characterized by the conditions

$$
\nabla G=0, \quad T=0,
$$

where $T$ is the torsion tensor of $\nabla$.
Theorem 3 [16]. The Levi Civita connection $\nabla$ of $G$ has the following expression in the local adapted frame $\left(\frac{\partial}{\partial y^{1}}, \ldots, \frac{\partial}{\partial y^{n}}, \frac{\delta}{\delta x^{1}}, \ldots, \frac{\delta}{\delta x^{n}}\right)$

$$
\left\{\begin{array}{l}
\nabla_{\frac{\partial}{\partial y^{2}}} \frac{\partial}{\partial y^{j}}=Q_{i j}^{h} \frac{\partial}{\partial y^{h}}, \nabla_{\frac{\delta}{\delta x^{i}}} \frac{\partial}{\partial y^{j}}=\Gamma_{i j}^{h} \frac{\partial}{\partial y^{h}}+P_{j i}^{h} \frac{\delta}{\delta x^{h}}  \tag{15}\\
\nabla_{\frac{\partial}{\partial y^{i}}} \frac{\delta}{\delta x^{j}}=P_{i j}^{h} \frac{\delta}{\delta x^{h}}, \nabla_{\frac{\delta}{\delta x^{i}}} \frac{\delta}{\delta x^{j}}=\Gamma_{i j}^{h} \frac{\delta}{\delta x^{h}}+S_{i j}^{h} \frac{\partial}{\partial y^{h}},
\end{array}\right.
$$

where the $M$-tensor fields $P_{i j}^{h}, Q_{i j}^{h}, S_{i j}^{h}$ are given by

$$
\left\{\begin{align*}
P_{i j}^{h} & =\frac{1}{2}\left(\frac{\partial G_{j k}}{\partial y^{i}}+H_{i l} R_{0 j k}^{l}\right) H^{k h}, S_{i j}^{h}=\frac{1}{2}\left(-R_{0 i j}^{h}-\frac{\partial G_{i j}}{\partial y^{k}} G^{k h}\right)  \tag{16}\\
Q_{i j}^{h} & =\frac{1}{2} G^{h k}\left(\frac{\partial H_{j k}}{\partial y^{i}}+\frac{\partial H_{i k}}{\partial y^{j}}-\frac{\partial H_{i j}}{\partial y^{k}}\right)
\end{align*}\right.
$$

Taking into account the expressions (3), (6) of $G_{i j}$ and $H_{i j}$ and by using the formulas (12), (14), (5) we may obtain the following expressions

$$
\left\{\begin{align*}
P_{i j}^{h}= & \frac{u^{\prime}}{2 u} \delta_{j}^{h} g_{0 i}+\frac{u v-c}{2 u^{2}} \delta_{i}^{h} g_{0 j}  \tag{17}\\
& -\frac{(c+u v) w}{2 v} g_{i j} y^{h}+\frac{v w(u v-c)+u w\left(u^{\prime} v-u v^{\prime}\right)}{2 u v} g_{0 i} g_{0 j} y^{h}
\end{align*}\right.
$$

$\left\{\begin{aligned} Q_{i j}^{h}= & -\frac{u^{\prime}}{2 u}\left(\delta_{j}^{h} g_{0 i}+\delta_{i}^{h} g_{0 j}\right) \\ & -\frac{v\left(u^{\prime}+2 u^{2} w\right)}{2 u^{3} w} g_{i j} y^{h}-\frac{v\left(2 u^{\prime} w+u w^{\prime}\right)}{2 u^{2} w} g_{0 i} g_{0 j} y^{h},\end{aligned}\right.$

$$
\left\{\begin{align*}
S_{i j}^{h}= & \frac{c-u v}{2} \delta_{j}^{h} g_{0 i}-\frac{c+u v}{2} \delta_{i}^{h} g_{0 j}  \tag{19}\\
& +\frac{u^{\prime} v}{2 u w} g_{i j} y^{h}+\frac{v\left(v^{\prime}-2 u v w\right)}{2 u w} g_{0 i} g_{0 j} y^{h} .
\end{align*}\right.
$$

Remark that in the obtained formulas we have used the formula (5) in order to replace the energy density $t$, such that it is not involved explicitly. Of course, we can replace $v, v^{\prime}, w, w^{\prime}$ as functions of $u, u^{\prime}, u^{\prime \prime}$ and $t$ but we obtain much more complicated expressions for $P_{i j}^{h}, Q_{i j}^{h}, S_{i j}^{h}$.

The curvature tensor field $K$ of the connection $\nabla$ is defined by the well known formula

$$
K(X, Y) Z=\nabla_{X} \nabla_{Y} Z-\nabla_{Y} \nabla_{X} Z-\nabla_{[X, Y]} Z, X, Y, Z \in \Gamma(T M) .
$$

By using the local frame $\left(\frac{\delta}{\delta x^{i}}, \frac{\partial}{\partial y^{i}}\right), i=1, \ldots, n$ we obtain, after a standard straightforward computation

$$
\begin{aligned}
& K\left(\frac{\delta}{\delta x^{i}}, \frac{\delta}{\delta x^{j}}\right) \frac{\delta}{\delta x^{k}}=X X X_{k i j}^{h} \frac{\delta}{\delta x^{j}}, K\left(\frac{\delta}{\delta x^{i}}, \frac{\delta}{\delta x^{j}}\right) \frac{\partial}{\partial y^{k}}=X X Y_{k i j}^{h} \frac{\partial}{\partial y^{h}}, \\
& K\left(\frac{\partial}{\partial y^{i}}, \frac{\partial}{\partial y^{j}}\right) \frac{\delta}{\delta x^{k}}=Y Y X_{k i j}^{h} \frac{\delta}{\delta x^{h}}, K\left(\frac{\partial}{\partial y^{i}}, \frac{\partial}{\partial y^{j}}\right) \frac{\partial}{\partial y^{k}}=Y Y Y_{k i j}^{h} \frac{\partial}{\partial y^{h}}, \\
& K\left(\frac{\partial}{\partial y^{i}}, \frac{\delta}{\delta x^{j}}\right) \frac{\delta}{\delta x^{k}}=Y X X_{k i j}^{h} \frac{\partial}{\partial y^{h}}, K\left(\frac{\partial}{\partial y^{i}}, \frac{\delta}{\delta x^{j}}\right) \frac{\partial}{\partial y^{k}}=Y X Y_{k i j}^{h} \frac{\delta}{\delta x^{h}}
\end{aligned}
$$

where

$$
\left\{\begin{array}{l}
X X X_{k i j}^{h}=R_{k i j}^{h}+P_{l k}^{h} R_{0 i j}^{l}+P_{l i}^{h} S_{j k}^{l}-P_{l j}^{h} S_{i k}^{l},  \tag{20}\\
X X Y_{k i j}^{h}=R_{k i j}^{h}+Q_{l k}^{h} R_{0 i j}^{l}+S_{i l}^{h} P_{k j}^{l}-S_{j l}^{h} P_{k i}^{l}, \\
Y Y X_{k i j}^{h}=\frac{\partial}{\partial y^{i}} P_{j k}^{h}-\frac{\partial}{\partial y^{j}} P_{i k}^{h}+P_{i l}^{h} P_{j k}^{l}-P_{j l}^{h} P_{i k}^{l}, \\
Y Y Y_{k i j}^{h}=\frac{\partial}{\partial y^{i}} Q_{j k}^{h}-\frac{\partial}{\partial y^{j}} Q_{i k}^{h}+Q_{i l}^{h} Q_{j k}^{l}-Q_{j l}^{h} Q_{i k}^{l}, \\
Y X X_{k i j}^{h}=\frac{\partial}{\partial y^{i}} S_{j k}^{h}+Q_{i l}^{h} S_{j k}^{l}-S_{j l}^{h} P_{i k}^{l}, \\
Y X Y_{k i j}^{h}=\frac{\partial}{\partial y^{i}} P_{k j}^{h}+P_{i l}^{h} P_{k j}^{l}-P_{l j}^{h} Q_{i k}^{l} .
\end{array}\right.
$$

Remark that, at a first step, the formulas for the expressions of $K$ contained also some other terms involving the Christoffel symbols $\Gamma_{i j}^{k}$. However, after some standard computations, we have been able to show that those other terms are zero.

Now we have to replace the expressions (17), (18), (19) of the $M$ tensor fields $P_{i j}^{h}, Q_{i j}^{h}, S_{i j}^{h}$ and the expressions (12), (14), (5) of the functions $v, w$ and of their derivatives in order to obtain the components from (20) as functions of $u, u^{\prime}, u^{\prime \prime}, u^{(3)}$ only. The obtained expressions are quite complicate and, at this stage, we decided to use the Mathematica package RICCI in order to do the necessary tensor calculations. It has been useful to consider $c, t, u, v, w, u^{\prime}, v^{\prime}, w^{\prime}, u^{\prime \prime}, v^{\prime \prime}, w^{\prime \prime}$, and $u^{(3)}$ as constants, the tangent vector $y$ as a first order tensor, the components $G_{i j}, H_{i j}$ as second order tensors and so on, on the tangent bundle to the Riemannian manifold $M$, the associated indices being $h, i, j, k, l, r, s$. It was not convenient to think of $u, v, w$ as functions of $t$ since RICCI did not make some useful factorizations after the command TensorSimplify.

The components of the Ricci tensor field of the connection $\nabla$, defined as $\operatorname{Ric}(Y, Z)=\operatorname{trace}(X \rightarrow K(X, Y) Z), X, Y, Z \in \Gamma(T M)$ are obtained as follows

$$
\begin{aligned}
& \operatorname{Ric}\left(\frac{\delta}{\delta x^{j}}, \frac{\delta}{\delta x^{k}}\right)=\operatorname{Ric} X X_{j k}=X X X_{k h j}^{h}+Y X X_{k h j}^{h}, \\
& \operatorname{Ric}\left(\frac{\partial}{\partial y^{j}}, \frac{\partial}{\partial y^{j}}\right)=\operatorname{Ric} Y Y_{j k}=Y Y Y_{k h j}^{h}-Y X Y_{k j h}^{h},
\end{aligned}
$$

$$
\operatorname{Ric}\left(\frac{\partial}{\partial y^{j}}, \frac{\delta}{\delta x^{k}}\right)=\operatorname{Ric}\left(\frac{\delta}{\delta x^{k}}, \frac{\partial}{\partial y^{j}}\right)=0 .
$$

The expressions of $\operatorname{Ric} X X_{j k}$, $\operatorname{Ric} Y Y_{j k}$ are quite complicate. In order to present a summary description of these expressions we introduce the function
(21) $a=n\left(u-2 t u^{\prime}\right)\left(2 c u-2 c t u^{\prime}-u^{2} u^{\prime}\right)+2\left(2 c t-u^{2}\right)\left(t u u^{\prime \prime}+u u^{\prime}-t u^{\prime 2}\right)$.

Then

$$
\begin{aligned}
\operatorname{Ric} X X_{j k} & =\frac{a}{2\left(u-2 t u^{\prime}\right)^{2}} g_{j k}+\alpha\left(t, u, u^{\prime}, u^{\prime \prime}, u^{(3)}\right) g_{0 j} g_{0 k} \\
\operatorname{Ric} Y Y_{j k} & =\frac{a}{2 u^{2}\left(u-2 t u^{\prime}\right)^{2}} g_{j k}+\beta\left(t, u, u^{\prime}, u^{\prime \prime}, u^{(3)}\right) g_{0 j} g_{0 k}
\end{aligned}
$$

where $\alpha, \beta$ are rational expressions in $t, u, u^{\prime}, u^{\prime \prime}, u^{(3)}$.
To study the conditions under which $(T M, G)$ is Einstein, we consider the differences

$$
\begin{aligned}
\text { Diff } X X_{j k} & =\operatorname{Ric} X X_{j k}-\frac{a}{2 u\left(u-2 t u^{\prime}\right)^{2}} G_{j k} \\
\text { Diff } Y Y_{j k} & =\operatorname{Ric} Y Y_{j k}-\frac{a}{2 u\left(u-2 t u^{\prime}\right)^{2}} H_{j k}
\end{aligned}
$$

Then we obtain

$$
\begin{aligned}
\text { Diff } X X_{j k}= & \frac{1}{2 u^{2}\left(u-2 t u^{\prime}\right)^{4}}\left[n\left(u^{2}-2 c t\right)\left(2 t u^{\prime}-u\right)\left(u^{2} u^{\prime \prime}-2 t u^{\prime 3}+2 u u^{\prime 2}\right)\right. \\
& -8 c^{2} t u^{3} u^{\prime}+4 c u^{5} u^{\prime}+16 c^{2} t^{2} u^{2} u^{\prime 2}+4 c t u^{4} u^{\prime 2}-6 u^{6} u^{\prime 2} \\
& -24 c^{2} t^{3} u u^{\prime 3}-8 c t^{2} u^{3} u^{\prime 3}+10 t u^{5} u^{\prime 3}+16 c^{2} t^{4} u^{\prime 4}-4 t^{2} u^{4} u^{\prime 4} \\
& -24 c^{2} t^{2} u^{3} u^{\prime \prime}+20 c t u^{5} u^{\prime \prime}-4 u^{7} u^{\prime \prime}+16 c^{2} t^{3} u^{2} u^{\prime} u^{\prime \prime}-4 t u^{6} u^{\prime} u^{\prime \prime} \\
& -16 c t^{3} u^{3} u^{\prime 2} u^{\prime \prime}+8 t^{2} u^{5} u^{\prime 2} u^{\prime \prime}-32 c^{2} t^{4} u^{2} u^{\prime \prime 2}+32 c t^{3} u^{4} u^{\prime \prime 2} \\
& -8 t^{2} u^{6} u^{\prime \prime 2}-8 c^{2} t^{3} u^{3} u^{(3)}+8 c t^{2} u^{5} u^{(3)}-2 t u^{7} u^{(3)} \\
& \left.+16 c^{2} t^{4} u^{2} u^{\prime} u^{(3)}-16 c t^{3} u^{4} u^{\prime} u^{(3)}+4 t^{2} u^{6} u^{\prime} u^{(3)}\right] g_{0 j} g_{0 k},
\end{aligned}
$$

Diff $Y Y_{j k}=\frac{1}{2 u^{2}\left(u^{2}-2 c t\right)\left(u-2 t u^{\prime}\right)^{2}}\left[n\left(u^{2}-2 c t\right)\left(2 t u^{\prime}-u\right)\right.$

$$
\begin{aligned}
& \times\left(u^{2} u^{\prime \prime}-2 t u^{3}+2 u u^{\prime 2}\right)+4 c u^{3} u^{\prime}-8 c t u^{2} u^{\prime 2}-6 u^{4} u^{\prime 2} \\
& +12 c t^{2} u u^{\prime 3}+10 t u^{3} u^{\prime 3}-8 c t^{3} u^{\prime 4}-4 t^{2} u^{2} u^{\prime 4}+12 c t u^{3} u^{\prime \prime} \\
& -4 u^{5} u^{\prime \prime}-8 c t^{2} u^{2} u^{\prime} u^{\prime \prime}-4 t u^{4} u^{\prime} u^{\prime \prime}+8 t^{2} u^{3} u^{\prime 2} u^{\prime \prime}+16 c t^{3} u^{2} u^{\prime \prime 2} \\
& -8 t^{2} u^{4} u^{\prime \prime 2}+4 c t^{2} u^{3} u^{(3)}-2 t u^{5} u^{(3)} \\
& \left.-8 c t^{3} u^{2} u^{\prime} u^{(3)}+4 t^{2} u^{2} u^{\prime} u^{(3)}\right] g_{0 j} g_{0 k} .
\end{aligned}
$$

Our task is to find a positive function $u(t)$ such that Diff $X X_{j k}=$ Diff $Y Y_{j k}=0$. It was hopeless to try to find directly a general common solution of the system of third order ordinary differential equations obtained by imposing the conditions Diff $X X_{j k}=\operatorname{Diff} Y Y_{j k}=0$. However, it is quite obvious that the function $u=$ constant is a solution of the obtained system. The case where $u=1$ has been discussed by the author in [12] and will be presented later on. The obtained Kähler Einstein structure on $T M$ in the case where $c<0$ or on a tube around the zero section in $T M$ in the case where $c>0$ is even locally symmetric. Another case which can be considered is that where $u^{2}=2 c t$. Remark that, in this case we have also $u-2 t u^{\prime}=0$. It is a singular case and it has been studied separately by the author and N. Papaghiuc in [16]. It will be presented later. Remark that the obtained Kähler is neither Einstein nor locally symmetric.

If we try to find another function $u$ for which Diff $X X_{j k}=\operatorname{Diff} Y Y_{j k}=0$ and which does not depend on the dimension $n$ of $M$, then we have to find the positive solutions of the second order differential equation

$$
\begin{equation*}
u^{2} u^{\prime \prime}-2 t u^{\prime 3}+2 u u^{\prime 2}=0 . \tag{22}
\end{equation*}
$$

Remark that if $u$ is a solution of this equation then $-u$ is a solution too.

We succeeded to find the general solution of the equation (22), then we studied the conditions under which the symmetric matrix $\left(G_{j k}\right)$ is positive, obtaining the following cases

1. $c<0, A>0$ and we have

$$
\begin{equation*}
u=A+\sqrt{A^{2}-2 c t}>0, v=\frac{1}{2 t}\left(A-\frac{4 c t}{A}-\sqrt{A^{2}-2 c t}\right)>0, \quad t \geq 0 . \tag{23}
\end{equation*}
$$

2. $c>0, A>0$ and we have

$$
\begin{equation*}
u=A \pm \sqrt{A^{2}-2 c t}, v=\frac{1}{2 t}\left(A-\frac{4 c t}{A} \mp \sqrt{A^{2}-2 c t}\right), \quad 0 \leq t<\frac{A^{2}}{2 c} . \tag{24}
\end{equation*}
$$

The solution $u=A-\sqrt{A^{2}-2 c t}$ has the property $u(0)=0$ and it should be excluded. However this solution can be studied as a singular case.

Remark that we may have $u>0, v \leq 0$ but the matrix $\left(G_{j k}\right)$ is still positive since, for $z, y \in T M, \tau(z)=\tau(y)=x \in M$, we have

$$
G_{(x, y)}(z, z)=u\|z\|^{2}+v\langle y, z\rangle^{2} \geq\|z\|^{2}(u+2 t v),
$$

where $\|z\|^{2}=g_{x}(z, z), 2 t=g_{x}(y, y)=\|y\|^{2}$. Hence it is enough to have $u+2 t v>0$.

Hence, we may state our main result
Theorem 4. 1. Assume that $(M, g)$ has constant negative sectional curvature $c$ and let $A>0$. Then $(T M, G, J)$, with $u$, $v$ given by (23) is a Kähler Einstein manifold.
2. Assume that $(M, g)$ has constant positive sectional curvature $c$ and let $A>0$. Then the tube around the zero section in $T M$, defined by the condition

$$
g_{j k} y^{j} y^{k}=2 t<\frac{A^{2}}{c}
$$

has a structure of Kähler Einstein manifold, if the functions $u, v$ are given by (24).

Remark. The case $c=0$ is not considered since $(M, g)$ is flat and we obtain just the flat Kähler structure on $T M$ defined in [3].

## 4. The holomorphic sectional curvature of $(T M, G, J)$

In this section we shall obtain the components of the curvature tensor field $K$ of $\nabla$ in the case where $u, v$ are given by (23), with $c<0, A>0$. Similar computations may be done in the remaining cases. Replacing in the formulas (20) $P, Q, S$ with their expressions (17), (18), (19), where $u$, $u^{\prime}, u^{\prime \prime}, u^{(3)}, v, v^{\prime}, v^{\prime \prime}, w, w^{\prime}, w^{\prime \prime}$ are computed by using (23), we obtain the
following quite simple expressions of the components (of course, we have used RICCI to do the corresponding tensor calculations)

$$
\left\{\begin{array}{l}
X X X_{k i j}^{h}=\frac{c}{2 A}\left(\delta_{i}^{h} G_{j k}-\delta_{j}^{h} G_{i k}\right), X X Y_{k i j}^{h}=\frac{c}{2 A}\left(g_{j k} G_{i}^{h}-g_{i k} G_{j}^{h}\right),  \tag{25}\\
Y Y X_{k i j}^{h}=\frac{c}{2 A}\left(g_{j k} H_{i}^{h}-g_{i k} H_{j}^{h}\right), Y Y Y_{k i j}^{h}=\frac{c}{2 A}\left(\delta_{i}^{h} H_{j k}-\delta_{j}^{h} H_{i k}\right), \\
Y X X_{k i j}^{h}=\frac{c}{2 A}\left(\delta_{i}^{h} G_{j k}+g_{i k} G_{j}^{h}+2 g_{i j} G_{k}^{h}\right), \\
Y X Y_{k i j}^{h}=-\frac{c}{2 A}\left(\delta_{j}^{h} H_{i k}+g_{j k} H_{i}^{h}+2 g_{i j} H_{k}^{h}\right) .
\end{array}\right.
$$

Recall that a Kähler manifold ( $M, g, J$ ) has holomorphic constant sectional curvature $k$ if its curvature tensor field $R$ is given by

$$
\begin{align*}
R(X, Y) Z= & \frac{k}{4}\{g(Y, Z) X-g(X, Z) Y+g(J Y, Z) J X \\
& -g(J X, Z) J Y+2 g(X, J Y) J Z\}, \quad X, Y, Z \in \chi(M) . \tag{26}
\end{align*}
$$

Comparing the expressions (25) of the components of $K$ with those obtained from (26), when we take $M \rightarrow T M, g \rightarrow G$ and for the vector fields $X, Y, Z$ involved in (28) we take the elements of the local frame $\left(\frac{\delta}{\delta x^{i}}, \frac{\partial}{\partial y^{2}}\right), i=1, \ldots, n$, we obtain a quite interesting result

Theorem 5. If $A>0, c<0$ and $(T M, G, J)$ has the Kähler Einstein structure defined by the expression (23) of $u$ and $v$, then $(T M, G, J)$ is a complex space form with negative constant holomorphic sectional curvature $\frac{2 c}{A}$.

Similar results are obtained in the cases where $u, v$ are given by (24).
The components of the Ricci tensor field Ric of $\nabla$ are

$$
\begin{aligned}
\operatorname{Ric} X X_{j k} & =\frac{(n+1) c}{A} G_{j k}, \quad \operatorname{Ric} Y Y_{j k}=\frac{(n+1) c}{A} H_{j k} \\
\operatorname{Ric} X Y_{j k} & =\operatorname{Ric} Y X_{j k}=0
\end{aligned}
$$

thus

$$
\text { Ric }=\frac{(n+1) c}{A} G .
$$

Remark. The equation (22) has also the singular solution $u=A t$, $A>0$, which is not a particular solution from (23) or (24). We have $u(0)=0$. This solution has been studied in [17]. The result is that the tube $\left(T_{A}^{0} M, G, J\right)$ is a locally symmetric Kähler Einstein manifold, in the case where $(M, g)$ is a space form with $c>0$, where $T_{A}^{0} M=\{y \in T M$, $\left.0<t<\frac{2 c}{A}\right\}$.

## 5. The case where $u=1$

In this section we shall study separately the case where $u=$ constant. In fact, we shall take $u=1$.

Theorem 6. If $u=1$, then the almost complex structure $J$ on $T M$ is integrable if and only if $(M, g)$ has constant sectional curvature $c$ and we have

$$
\begin{equation*}
v=-c . \tag{27}
\end{equation*}
$$

If $c<0$ we obtain a Kähler Einstein structure on whole TM. In the case where the constant $c$ is positive we have a Kähler structure in the tube around the zero section in TM defined by

$$
\begin{equation*}
t<\frac{1}{2 c} . \tag{28}
\end{equation*}
$$

Then the components $G_{i j}, H_{i j}$ of the $M$-tensor fields on $T M$, defining the Riemannian metric $G$ are given by

$$
\begin{equation*}
G_{i j}=g_{i j}-c g_{0 i} g_{0 j}, \quad H_{i j}=g_{i j}+\frac{c}{1-2 c t} g_{0 i} g_{0 j} . \tag{29}
\end{equation*}
$$

From the expression of $G_{i j}$ it follows that the symmetric matrix $\left(G_{i j}\right)$ is positive if $c<0$ and from the expression of $H_{i j}$ it follows that we have a Kähler structure even when $c>0$ but only in the region of $T M$ where $g_{i j} y^{i} y^{j}=2 t<\frac{1}{c}$.

The Levi Civita connection of the metric $G$ may be obtained easily.
Theorem 7. The Levi Civita connection $\nabla$ of the Kähler manifold $(T M, G, J)$ is given by the formulas

$$
\begin{cases}\nabla_{\frac{\partial}{\partial y^{i}}} \frac{\partial}{\partial y^{j}}=Q_{i j}^{h} \frac{\partial}{\partial y^{h}}, & \nabla_{\frac{\delta}{\delta x^{i}}} \frac{\partial}{\partial y^{j}}=\Gamma_{i j}^{h} \frac{\partial}{\partial y^{h}}+P_{j i}^{h} \frac{\delta}{\delta x^{h}},  \tag{30}\\ \nabla_{\frac{\partial}{\partial y^{i}}} \frac{\delta}{\delta x^{j}}=P_{i j}^{h} \frac{\delta}{\delta x^{h}}, & \nabla_{\frac{\delta}{\delta x^{i}}} \frac{\delta}{\delta x^{j}}=\Gamma_{i j}^{h} \frac{\delta}{\delta x^{h}}+S_{i j}^{h} \frac{\partial}{\partial y^{h}},\end{cases}
$$

where the $M$-tensor fields $P_{i j}^{h}, Q_{i j}^{h}, S_{i j}^{h}$ are given by

$$
\left\{\begin{array}{l}
P_{i j}^{h}=-c \delta_{i}^{h} g_{0 j}-\frac{c^{2}}{1-2 c t} g_{0 i} g_{0 j} y^{h}=-c g_{0 j} H_{i}^{h},  \tag{31}\\
Q_{i j}^{h}=c g_{i j} y^{h}+\frac{c^{2}}{1-2 c t} g_{0 i} g_{0 j} y^{h}=c y^{h} H_{i j}, \\
S_{i j}^{h}=c \delta_{j}^{h} g_{0 i}-c^{2} g_{0 i} g_{0 j} y^{h}=c g_{0 i} G_{j}^{h} .
\end{array}\right.
$$

If $K$ is the curvature tensor field of the connection $\nabla$, then we obtain by a straightforward computation

$$
\left\{\begin{array}{l}
K\left(\frac{\delta}{\delta x^{i}}, \frac{\delta}{\delta x^{j}}\right) \frac{\delta}{\delta x^{k}}=c\left(\delta_{i}^{h} G_{j k}-\delta_{j}^{h} G_{i k}\right) \frac{\delta}{\delta x^{h}}  \tag{32}\\
K\left(\frac{\delta}{\delta x^{i}}, \frac{\delta}{\delta x^{j}}\right) \frac{\partial}{\partial y^{k}}=c\left(g_{j k} G_{i}^{h}-g_{i k} G_{j}^{h}\right) \frac{\partial}{\partial y^{h}}, \\
K\left(\frac{\partial}{\partial y^{i}}, \frac{\partial}{\partial y^{j}}\right) \frac{\delta}{\delta x^{k}}=c\left(g_{j k} H_{i}^{h}-g_{i k} H_{j}^{h}\right) \frac{\delta}{\delta x^{h}}, \\
K\left(\frac{\partial}{\partial y^{i}}, \frac{\partial}{\partial y^{j}}\right) \frac{\partial}{\partial y^{k}}=c\left(\delta_{i}^{h} H_{j k}-\delta_{j}^{h} H_{i k}\right) \frac{\partial}{\partial y^{h}}, \\
K\left(\frac{\partial}{\partial y^{i}}, \frac{\delta}{\delta x^{j}}\right) \frac{\delta}{\delta x^{k}}=c g_{i j} G_{k}^{h} \frac{\partial}{\partial y^{h}}, \\
K\left(\frac{\partial}{\partial y^{i}}, \frac{\delta}{\delta x^{j}}\right) \frac{\partial}{\partial y^{k}}=-c g_{i j} H_{k}^{h} \frac{\delta}{\delta x^{h}} .
\end{array}\right.
$$

Finally, we obtain the Ricci tensor field of $\nabla$, defined as $\operatorname{Ric}(Y, Z)=$ $\operatorname{trace}(X \rightarrow K(X, Y) Z), X, Y, Z \in \Gamma(T M)$. It follows

$$
\begin{align*}
& \operatorname{Ric}\left(\frac{\delta}{\delta x^{i}}, \frac{\delta}{\delta x^{j}}\right)=c n G_{j k}, \quad \operatorname{Ric}\left(\frac{\partial}{\partial y^{i}}, \frac{\partial}{\partial y^{j}}\right)=c n H_{j k},  \tag{33}\\
& \operatorname{Ric}\left(\frac{\partial}{\partial y^{i}}, \frac{\delta}{\delta x^{j}}\right)=0 .
\end{align*}
$$

It follows that Ric $=c n G$.
By using the the expression (32) of $K$, we computed its the covariant derivatives with respect to the connection $\nabla$, by using the vector fields $\frac{\delta}{\delta x^{h}}$ and $\frac{\partial}{\partial y^{\hbar}}$, and and we obtained that in all twelve cases the result is zero. Thus we may state

Theorem 8. If $(M, g)$ has constant negative sectional curvature and the components of the metric $G$ are given by (29) then $(T M, G)$ is a locally symmetric space. If $(M, g)$ has constant positive sectional curvature and the components of the metric $G$ are given by (29) then the tube around the zero section in TM defined by the condition (28), endowed with the metric $G$, is a locally symmetric Riemannian manifold.

Remark. It is well known that an irreducible locally symmetric Riemannian manifold is automatically Einstein, thus our result Ric $=c n$ $G$ is a consequence of the Theorem 8. However, it seemed to us that it is simpler to compute the traces of $K$ in order to obtain Ric than to to compute the components of $\nabla K$.

## 6. The case where $v=u^{\prime}$

In this section we shall present the results obtained by the author and N. Papaghiuc in [16] in the case where $v=u^{\prime}$.

First of all we obtained the following integrability condition for the almost complex structure $J$ on $T M$.

Theorem 9. The almost complex structure $J$ on $T M$ is integrable if and only if $(M, g)$ has positive constant sectional curvature $c$ and the function $u(t)$ satisfies the ordinary differential equation

$$
\begin{equation*}
2 t\left(u^{\prime}\right)^{2}=c \tag{34}
\end{equation*}
$$

The general solution of the differential equation (34) may be obtained easily. Since we look for a solution $u$ defined for $t>0$, for which $u>0$, $u^{\prime}>0$, we may take

$$
\begin{equation*}
u^{\prime}=\sqrt{\frac{c}{2 t}}, \quad u=\sqrt{2 c t}, \quad w=-\frac{1}{4 t \sqrt{2 c t}} \tag{35}
\end{equation*}
$$

Remark that the functions $u, u^{\prime}, w$ are smooth only on the nonzero tangent vectors of $M$. Hence we obtain, in fact, a Kähler structure only on the manifold $T_{0} M=$ the bundle of nonzero tangent vectors to $M$.

In order to obtain the expression of the Levi Civita connection $\nabla$ on $T M$, determined by the metric $G$ we shall introduce, for convenience, the following $M$-tensor fields on $T_{0} M$

$$
\begin{equation*}
a_{i j}=g_{i j}-\frac{1}{2 t} g_{0 i} g_{0 j}, \quad a_{i}^{k}=\delta_{i}^{k}-\frac{1}{2 t} g_{0 i} y^{k} \tag{36}
\end{equation*}
$$

Remark that we have

$$
a_{i 0}=a_{0 i}=a_{i j} y^{j}=0, \quad a_{i j}=a_{i}^{k} g_{k j}=a_{i}^{k} a_{k j}
$$

Then we obtain

$$
\left\{\begin{array}{l}
G_{i j}=\sqrt{2 c t} g_{i j}+\sqrt{\frac{c}{2 t}} g_{0 i} g_{0 j}=\sqrt{2 c t}\left(a_{i j}+\frac{1}{t} g_{0 i} g_{0 j}\right),  \tag{37}\\
H_{i j}=\frac{1}{\sqrt{2 c t}} g_{i j}-\frac{1}{4 t \sqrt{2 c t}} g_{0 i} g_{0 j}=\frac{1}{\sqrt{2 c t}}\left(a_{i j}+\frac{1}{4 t} g_{0 i} g_{0 j}\right), \\
H^{j k}=\frac{1}{\sqrt{2 c t}} g^{j k}-\frac{1}{4 t \sqrt{2 c t}} y^{j} y^{k}, G^{j k}=\sqrt{2 c t} g^{j k}+\sqrt{\frac{c}{2 t}} y^{j} y^{k} .
\end{array}\right.
$$

Theorem 10. The Levi Civita connection of the Kähler manifold $\left(T_{0} M, G, J\right)$ is given by

$$
\begin{aligned}
\nabla_{\frac{\partial}{\partial y^{i}}} \frac{\partial}{\partial y^{j}} & =\left(-\frac{1}{4 t} g_{0 i} \delta_{j}^{h}-\frac{1}{4 t} g_{0 j} \delta_{i}^{h}+\frac{1}{8 t^{2}} g_{0 i} g_{0 j} y^{h}\right) \frac{\partial}{\partial y^{h}} \\
\nabla_{\frac{\delta}{\delta x^{i}}} \frac{\partial}{\partial y^{j}} & =\Gamma_{i j}^{h} \frac{\partial}{\partial y^{h}}+\left(\frac{1}{4 t} g_{i j} y^{h}+\frac{1}{4 t} g_{0 j} \delta_{i}^{h}-\frac{1}{8 t^{2}} g_{0 i} g_{0 j} y^{h}\right) \frac{\delta}{\delta x^{h}} \\
& =\Gamma_{i j}^{h} \frac{\partial}{\partial y^{h}}+\left(\frac{1}{4 t} a_{i j} y^{h}+\frac{1}{4 t} \delta_{i}^{h} g_{0 j}\right) \frac{\delta}{\delta x^{h}} \\
\nabla_{\frac{\partial}{\partial y^{i}}} \frac{\delta}{\delta x^{j}} & =\left(\frac{1}{4 t} g_{i j} y^{h}+\frac{1}{4 t} g_{0 i} \delta_{j}^{h}-\frac{1}{8 t^{2}} g_{0 i} g_{0 j} y^{h}\right) \frac{\delta}{\delta x^{h}} \\
& =\left(\frac{1}{4 t} a_{i j} y^{h}+\frac{1}{4 t} \delta_{j}^{h} g_{0 i}\right) \frac{\delta}{\delta x^{h}}, \\
\nabla_{\frac{\delta}{\delta x^{i}}} \frac{\delta}{\delta x^{j}} & =\Gamma_{i j}^{h} \frac{\delta}{\delta x^{h}}-c\left(g_{i j} y^{h}+\delta_{i}^{h} g_{0 j}\right) \frac{\partial}{\partial y^{h}}
\end{aligned}
$$

Then the expression of the operator $J$ is given by

$$
\begin{aligned}
J \frac{\delta}{\delta x^{i}} & =\left(\sqrt{2 c t} \delta_{i}^{k}+\sqrt{\frac{c}{2 t}} g_{0 i} y^{k}\right) \frac{\partial}{\partial y^{k}} \\
J \frac{\partial}{\partial y^{i}} & =\left(-\frac{1}{\sqrt{2 c t}} \delta_{i}^{k}+\frac{1}{4 t \sqrt{2 c t}} g_{0 i} y^{k}\right) \frac{\delta}{\delta x^{k}}
\end{aligned}
$$

and it can be checked easily that $\nabla J=0$.

The expression of the curvature tensor field $K$ of the Levi Civita connection $\nabla$ on $T_{0} M$ is obtained easily by a straightforward computation.

Theorem 11. The local coordinate expression of the curvature tensor field $K$ of the Kähler manifold $\left(T_{0} M, G, J\right)$ is given in the adapted local frame $\left(\frac{\partial}{\partial y^{i}}, \frac{\delta}{\delta x^{i}}\right)$ by

$$
\left\{\begin{array}{l}
K\left(\frac{\partial}{\partial y^{i}}, \frac{\partial}{\partial y^{j}}\right) \frac{\partial}{\partial y^{k}}=\frac{1}{4 t} K_{k i j}^{h} \frac{\partial}{\partial y^{h}}, K\left(\frac{\partial}{\partial y^{i}}, \frac{\partial}{\partial y^{j}}\right) \frac{\delta}{\delta x^{k}}=\frac{1}{4 t} K_{k i j}^{h} \frac{\delta}{\delta x^{h}},  \tag{38}\\
K\left(\frac{\partial}{\partial y^{i}}, \frac{\delta}{\delta x^{j}}\right) \frac{\partial}{\partial y^{k}}=\frac{1}{4 t} S_{k i j}^{h} \frac{\delta}{\delta x^{h}}, K\left(\frac{\partial}{\partial y^{i}}, \frac{\delta}{\delta x^{j}}\right) \frac{\delta}{\delta x^{k}}=-\frac{c}{2} S_{k i j}^{h} \frac{\partial}{\partial y^{h}}, \\
K\left(\frac{\delta}{\delta x^{i}}, \frac{\delta}{\delta x^{j}}\right) \frac{\partial}{\partial y^{k}}=\frac{c}{2} K_{k i j}^{h} \frac{\partial}{\partial y^{h}}, K\left(\frac{\delta}{\delta x^{i}}, \frac{\delta}{\delta x^{j}}\right) \frac{\delta}{\delta x^{k}}=\frac{c}{2} K_{k i j}^{h} \frac{\delta}{\delta x^{h}},
\end{array}\right.
$$

where we have denoted

$$
K_{k i j}^{h}=\frac{1}{c}\left\{R_{k i j}^{h}-\frac{1}{2 t} g_{0 k} R_{0 i j}^{h}+\frac{1}{2 t} g_{l k} R_{0 i j}^{l} y^{h}\right\}=a_{i}^{h} a_{j k}-a_{j}^{h} a_{i k}
$$

and

$$
\begin{align*}
S_{k i j}^{h}= & g_{i k} \delta_{j}^{h}+g_{j k} \delta_{i}^{h}+\frac{1}{2 t^{2}} g_{0 i} g_{0 j} g_{0 k} y^{h}  \tag{40}\\
& -\frac{1}{2 t}\left[g_{0 i} g_{j k} y^{h}+g_{0 j} g_{i k} y^{h}+g_{0 i} g_{0 k} \delta_{j}^{h}+g_{0 j} g_{0 k} \delta_{i}^{h}\right] \\
= & a_{i}^{h} a_{j k}+a_{j}^{h} a_{i k} .
\end{align*}
$$

From the above formulas, we get by a straightforward computation that the local coordinate expression of the Ricci tensor $S(Y, Z)=$ trace $(X \rightarrow K(X, Y) Z)$ in the local frame adapted to the direct sum decomposition (1) is given by

$$
\left\{\begin{array}{l}
S\left(\frac{\partial}{\partial y^{i}}, \frac{\partial}{\partial y^{j}}\right)=-\frac{1}{2 t}\left[g_{i j}-\frac{1}{2 t} g_{0 i} g_{0 j}\right]=-\frac{1}{2 t} a_{i j}  \tag{41}\\
S\left(\frac{\delta}{\delta x^{i}}, \frac{\delta}{\delta x^{j}}\right)=-c\left[g_{i j}-\frac{1}{2 t} g_{0 i} g_{0 j}\right]=-c a_{i j} \\
S\left(\frac{\partial}{\partial y^{i}}, \frac{\delta}{\delta x^{j}}\right)=0
\end{array}\right.
$$

Comparing the obtained expressions with the expressions (37) of the components of $G$ we obtain

Proposition 12. The Kählerian manifold $\left(T_{0} M, G, J\right)$ cannot be an Einstein manifold.

From the expression (38) of $K$ it follows also
Proposition 13. The Kählerian manifold $\left(T_{0} M, G, J\right)$ cannot have constant holomorphic sectional curvature.

Finally, by computing the covariant derivative of $K$ with respect to $\nabla$, we obtain

Proposition 14. The Kählerian manifold $\left(T_{0} M, G, J\right)$ cannot be locally symmetric.

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v. oproiu

FACULTY OF MATHEMATICS
university "Al.i.cuza", iaşi
ROMANIA
E-mail: voproiu@uaic.ro
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